

# KSETA Workshop 2013

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# Data Analysis in Hardware

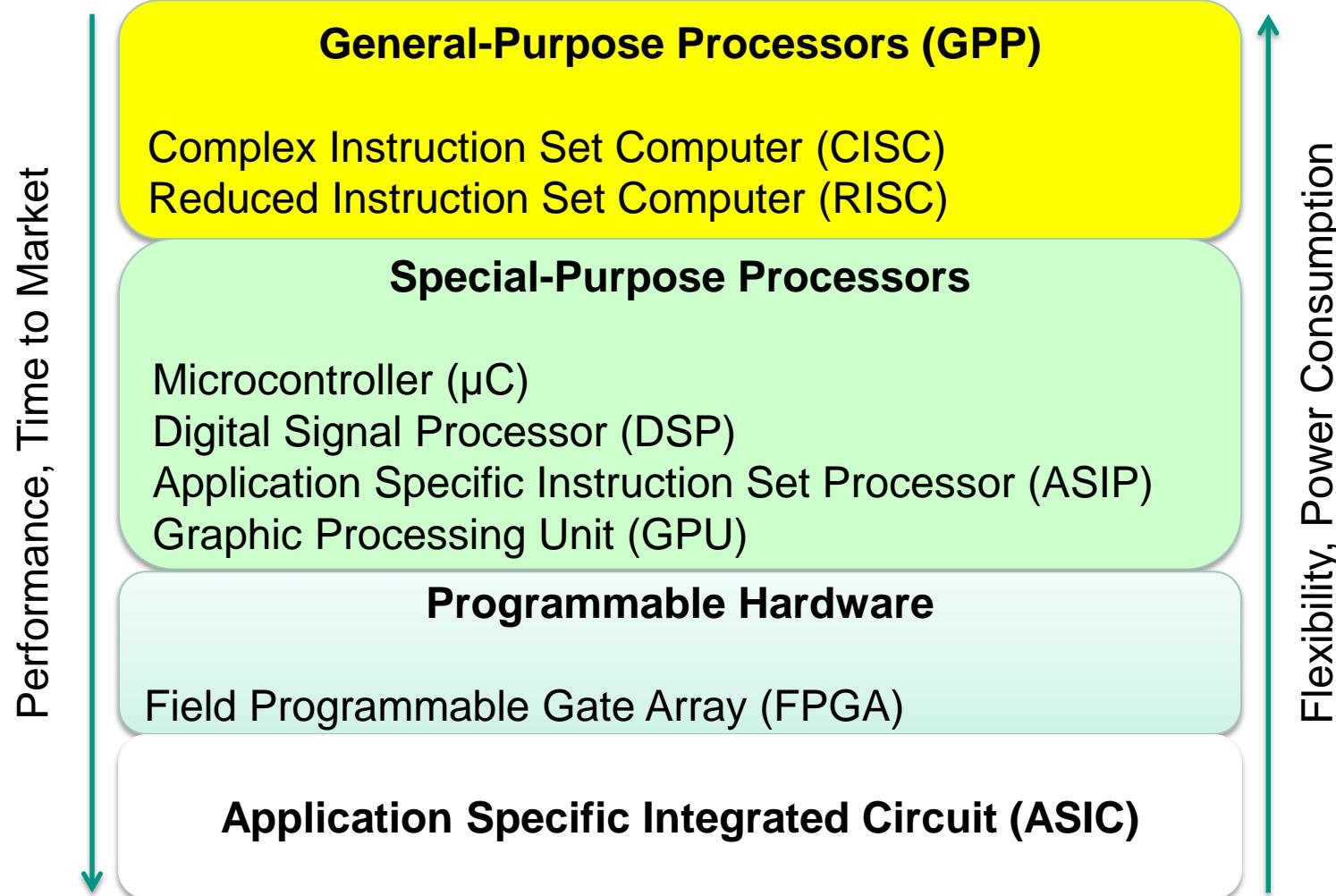
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# A Tutorial on VHDL and FPGAs

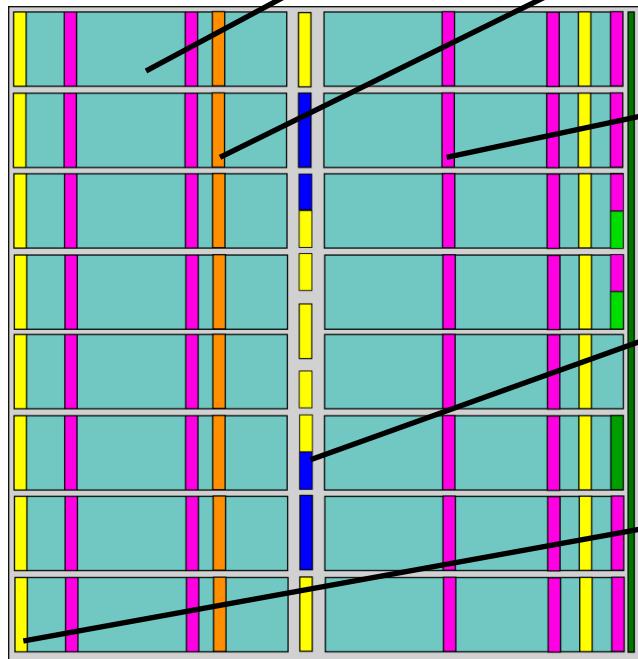
# Overview

- Technologies Overview
- Introduction to Field Programmable Gate Arrays (FPGAs)
  - Technology: Xilinx Virtex5
  - Example: Full Adder
- FPGA Design Flow
  - VHDL
  - Xilinx ISE

# Comparison between Technologies

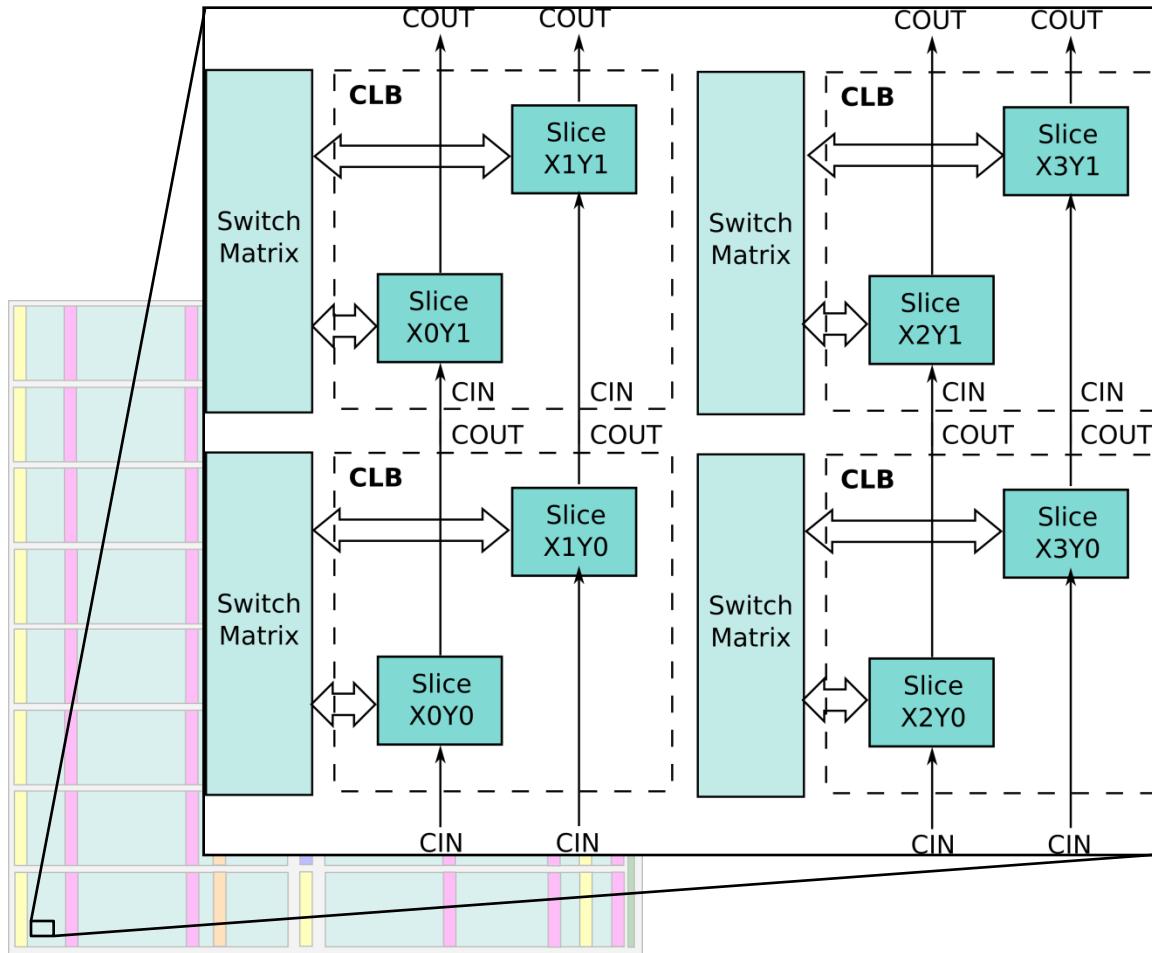


# Example: Xilinx Virtex5 110T



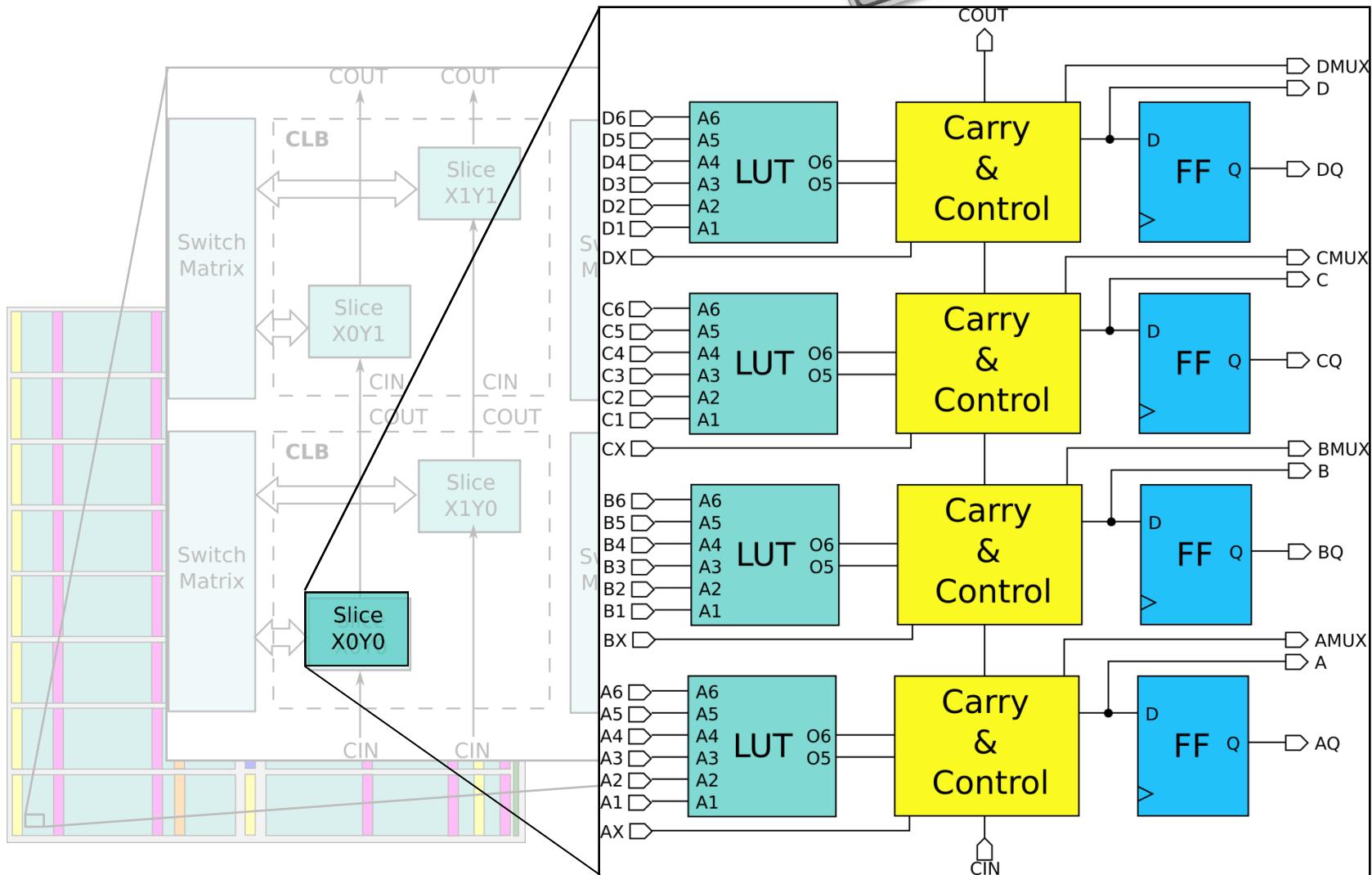
- Configurable Logic Block (CLB)
- Digital Signal Processor (DSP)
- Block RAM (BRAM)
- Digital Clock Memory (DCM)
- I/O Bank

# Example: Xilinx Virtex5 110T



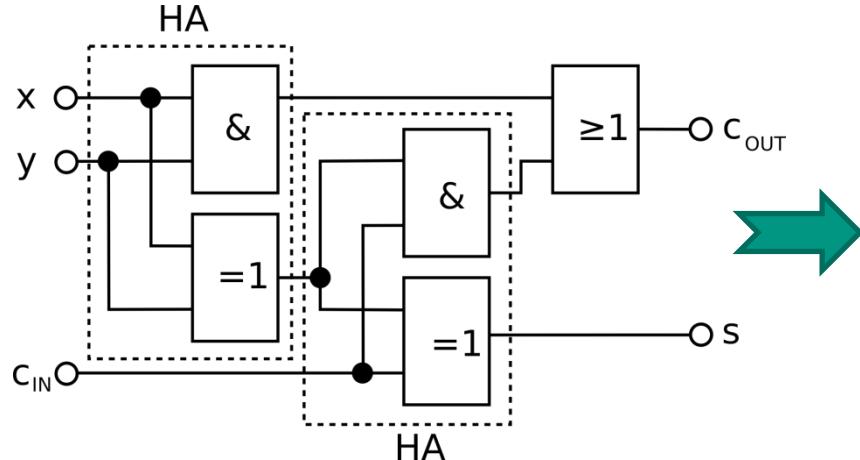
- One CLB consists of two Slices
- Programmable Switch Matrix
- Fast local routing inside a CLB
- Global routing between CLBs

# Example: Xilinx Virtex5 110T



# How to map a full adder into a Slice

## ■ Step 1: Create a truth table



X	Y	Cin	S	Cout
0	0	0	0	0
0	0	1	1	0
0	1	0	1	0
0	1	1	0	1
1	0	0	1	0
1	0	1	0	1
1	1	0	0	1
1	1	1	1	1

# How to map a full adder into a Slice

## ■ Step 2: Produce Disjunctive Normal Form (DNF)

X	Y	Cin	S	Cout
0	0	0	0	0
0	0	1	1	0
0	1	0	1	0
0	1	1	0	1
1	0	0	1	0
1	0	1	0	1
1	1	0	0	1
1	1	1	1	1



$$s = (\bar{x} \wedge \bar{y} \wedge Cin) \vee (\bar{x} \wedge y \wedge \overline{Cin}) \vee \\ (x \wedge \bar{y} \wedge \overline{Cin}) \vee (x \wedge y \wedge Cin)$$

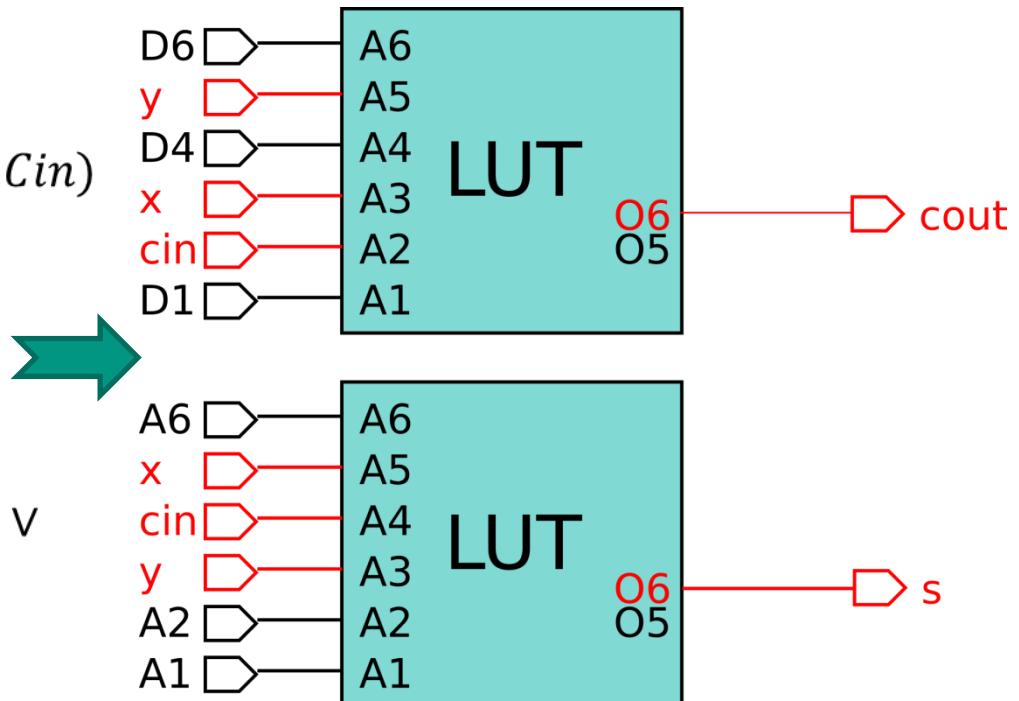
$$Cout = (\bar{x} \wedge y \wedge Cin) \vee (x \wedge y) \vee (x \wedge Cin)$$

# How to map a full adder into a Slice

- Step 2: Realization with two Lookup Tables

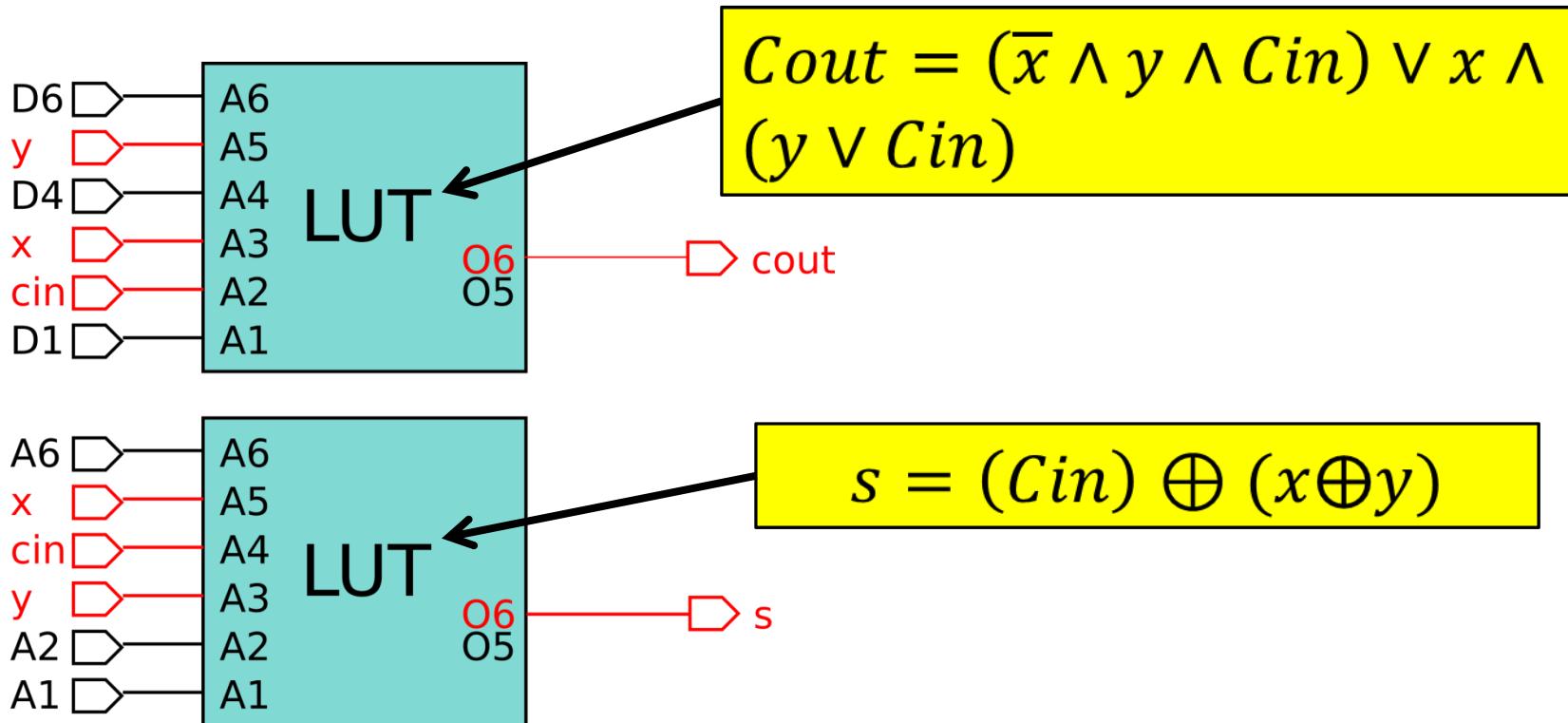
$$Cout = (\bar{x} \wedge y \wedge Cin) \vee (x \wedge y) \vee (x \wedge Cin)$$

$$s = (\bar{x} \wedge \bar{y} \wedge Cin) \vee (\bar{x} \wedge y \wedge \overline{Cin}) \vee \\ (\bar{x} \wedge \bar{y} \wedge \overline{Cin}) \vee (x \wedge y \wedge Cin)$$



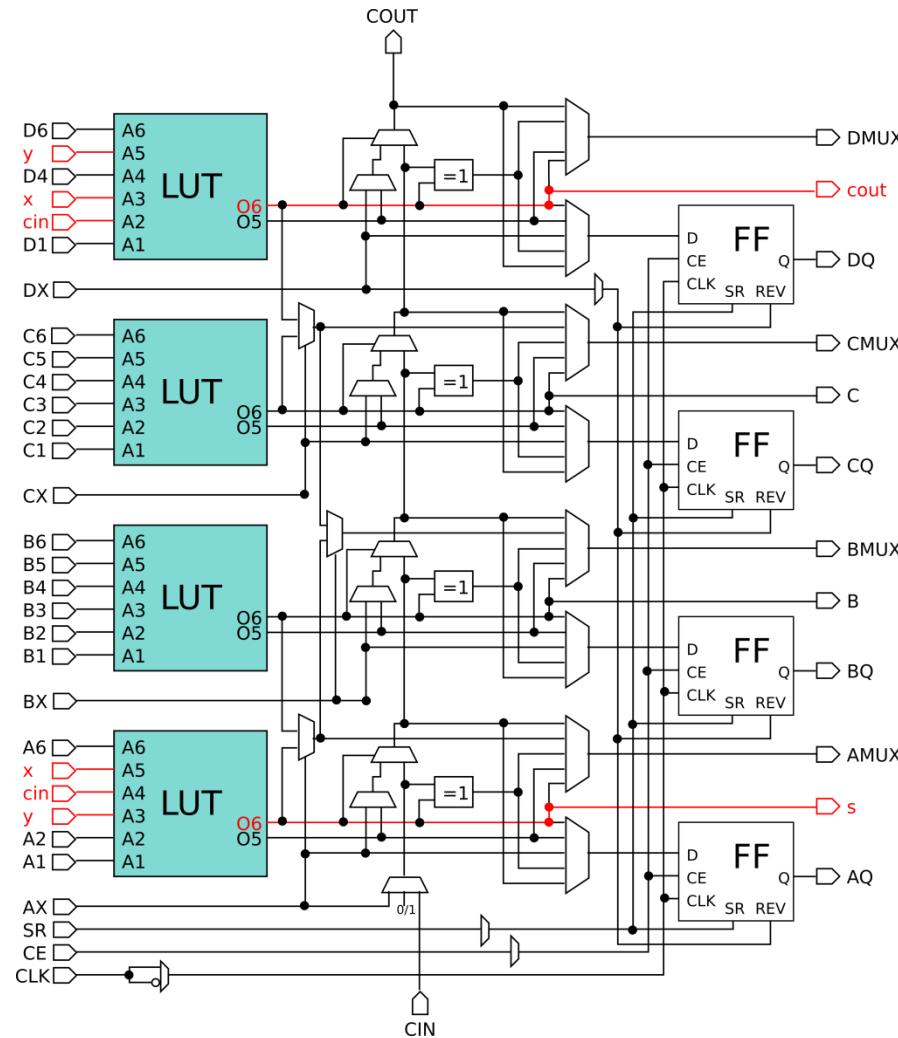
# How to map a full adder into a Slice

- Step 2: Realization with two Lookup Tables

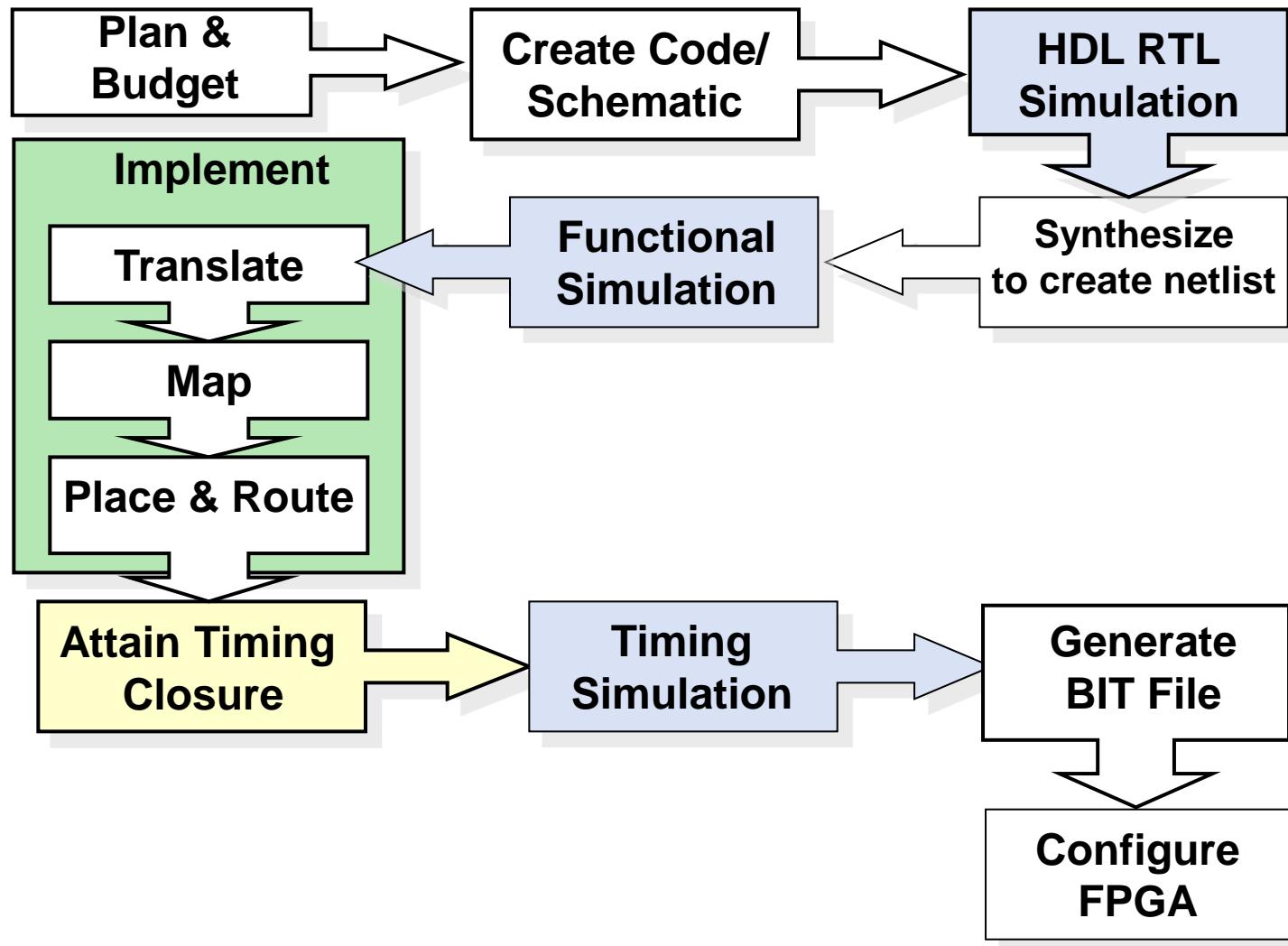


Generated by Xilinx ISE 14.2

# Full adder in a Virtex5 SliceL

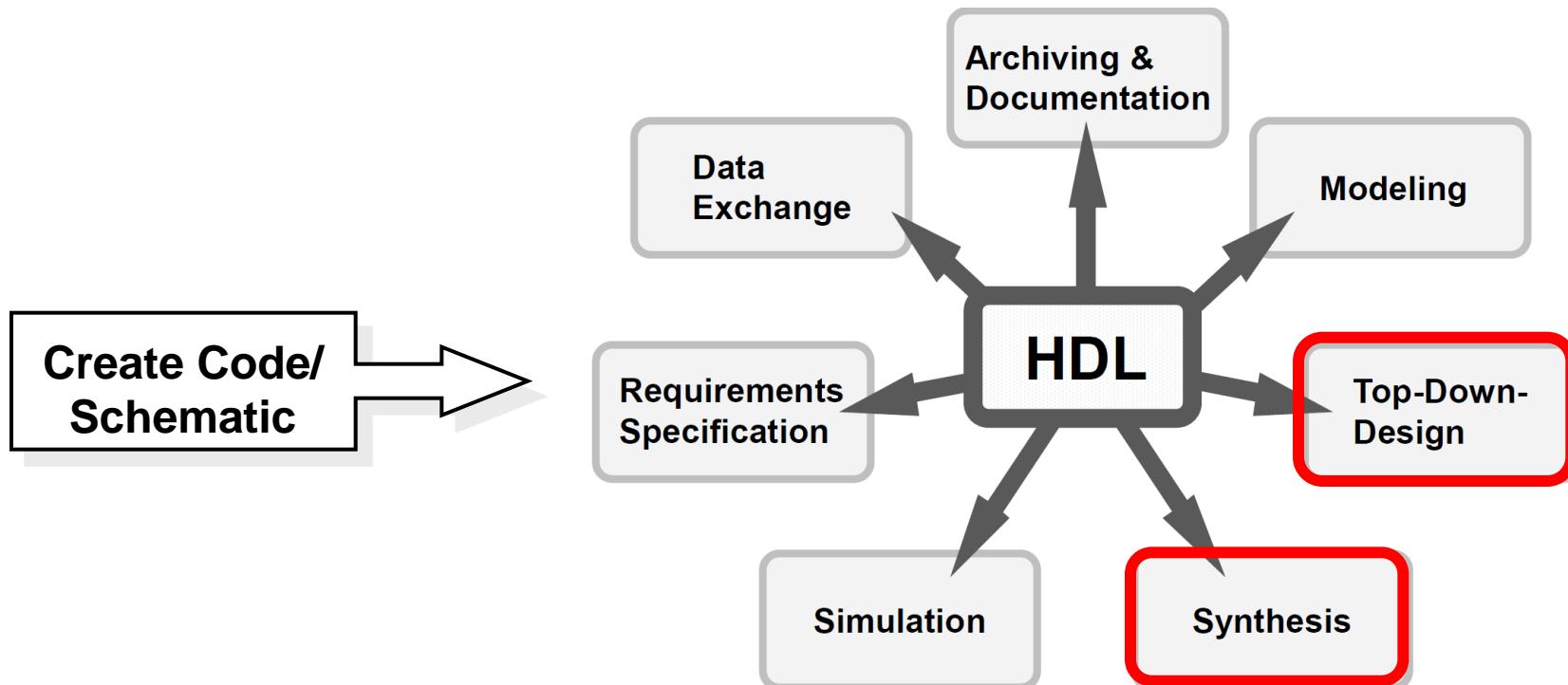


# FPGA Design Flow



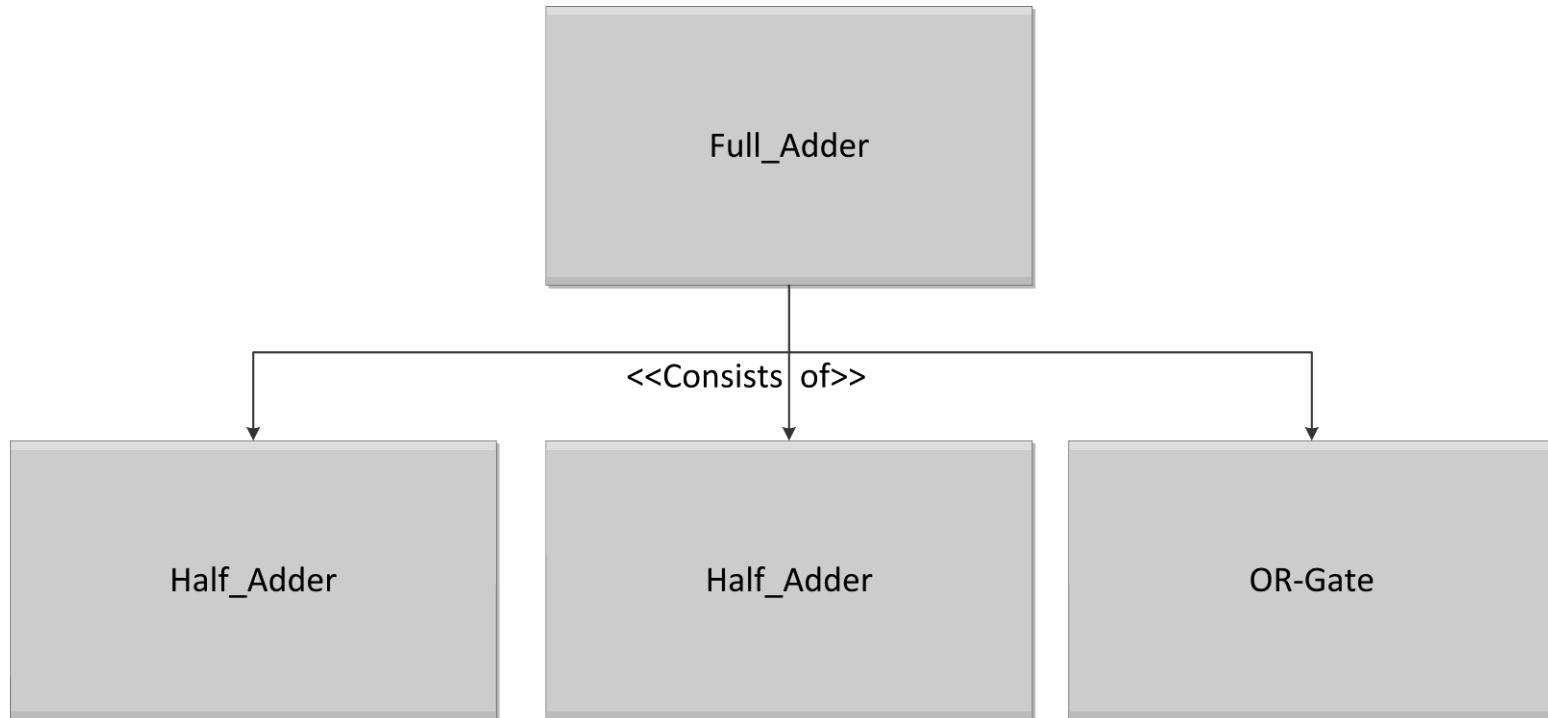
# VHDL-Introduction

- VHSIC HDL – Very high Speed Integrated Circuits Hardware Description Language
- Enforced by the US-Department of Defense for documentation of ASICs



# VHDL - Top-Down Design

- Hardware Designs are typically described in a top-down fashion



# VHDL-Entity

- Description of a module's interface

- Ports as mean of communication

- Name
- Direction
- Type

```

1 entity full_adder
2     Port(
3         x           : in  std_logic;
4         y           : in  std_logic;
5         cin         : in  std_logic;
6         s           : out std_logic;
7         cout        : out std_logic
8     );
9 end full_adder;

```

Entity description of full adder in VHDL



Graphical representation of full adder entity

# VHDL-Signals

## ■ Special Container for Data in VHDL

- Parallel assignments of values
- Connection between Modules
- Coupling with timing information for simulations

```
1 signal name : type;
```

VHDL signal declaration syntax

```
1 signal result : std_logic;
```

VHDL signal declaration

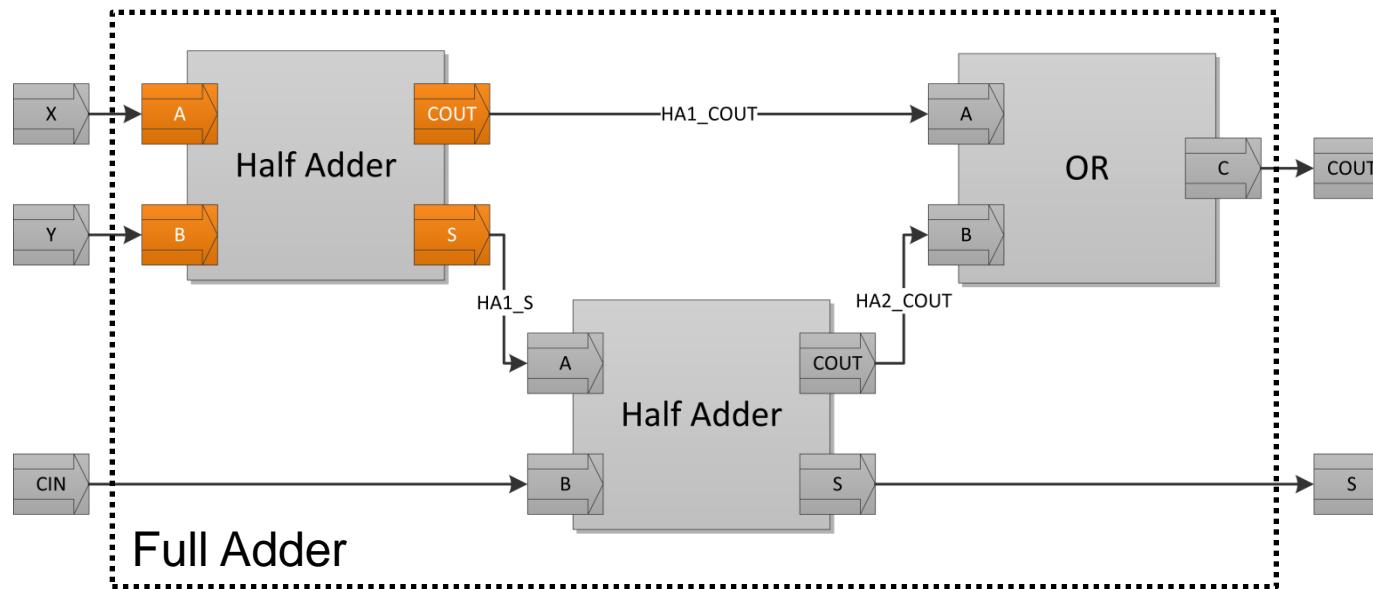
# VHDL-Architecture

- Couples Entities with
  - Structural description
    - Declaration of used modules
    - Instantiation of modules
    - Connection of modules
  - Behavioural description
    - What does the module do ?

```
1 architecture structure of full_adder is
2 ...
3 end structure full_adder;
```

Architecture declaration of full adder in VHDL

# VHDL-Structural Description(1)



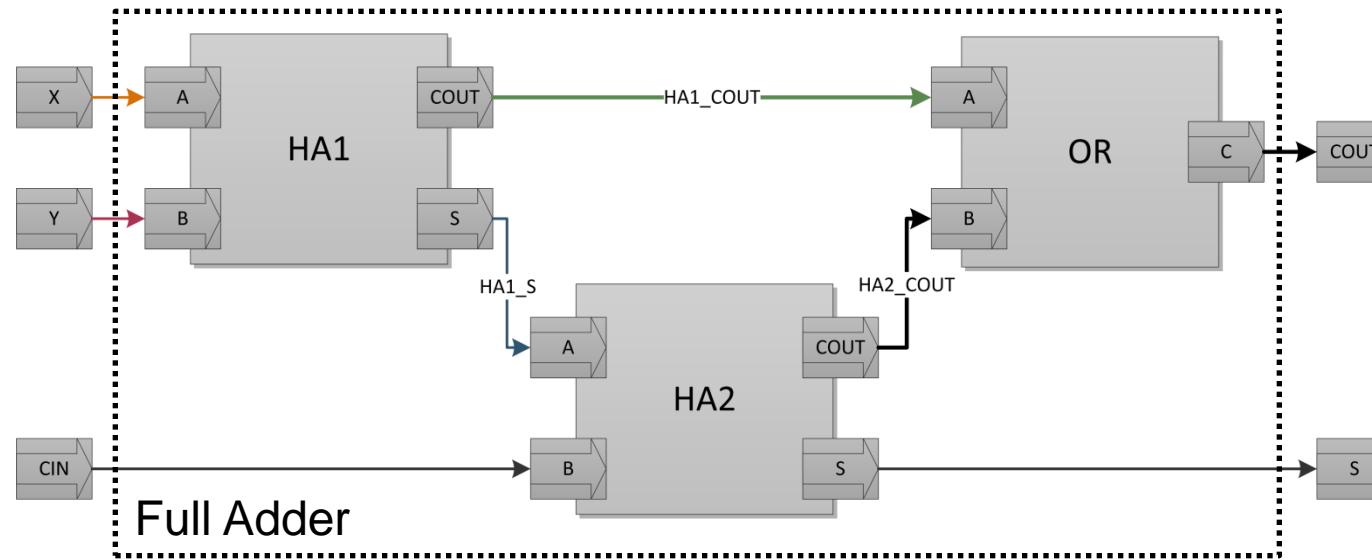
```

1 component half_adder
2   Port(
3     a      : in  std_logic;
4     b      : in  std_logic;
5     s      : out std_logic;
6     cout  : out std_logic
7   );
8 component half_adder;

```

Component declaration of full adder entity in VHDL

# VHDL-Structural Description(2)

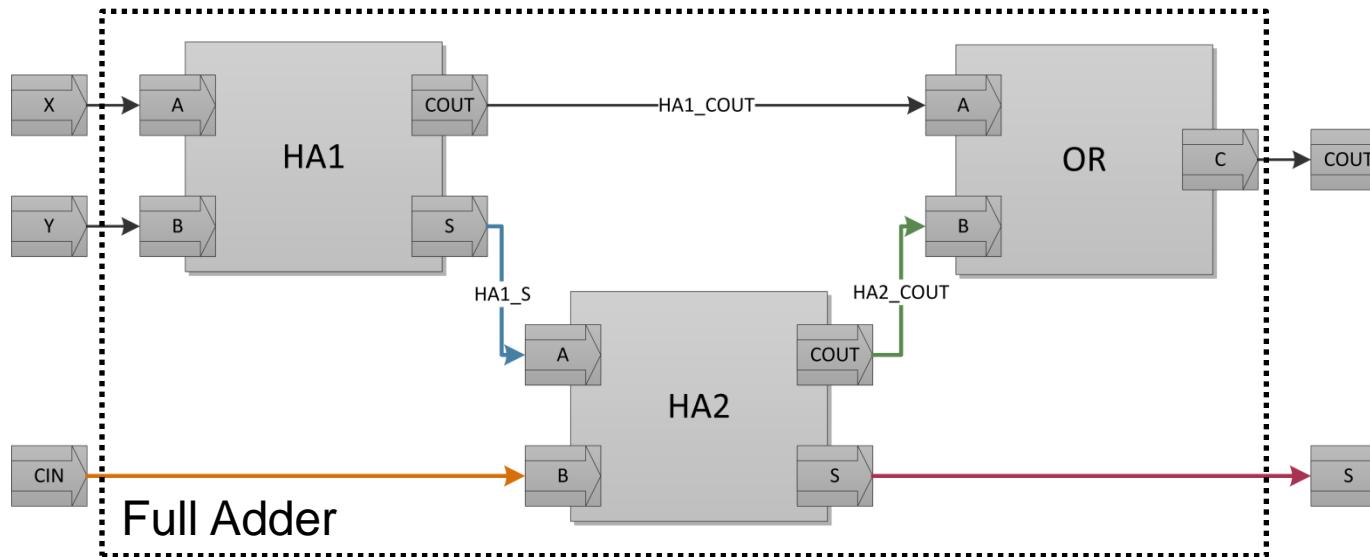


```

1 ha1 : half_adder
2     Port Map(
3         a          => x,
4         b          => y,
5         s          => ha1_s,
6         cout       => ha1_cout
7     );
  
```

Component instantiation of half adder in VHDL

# VHDL-Structural Description(3)

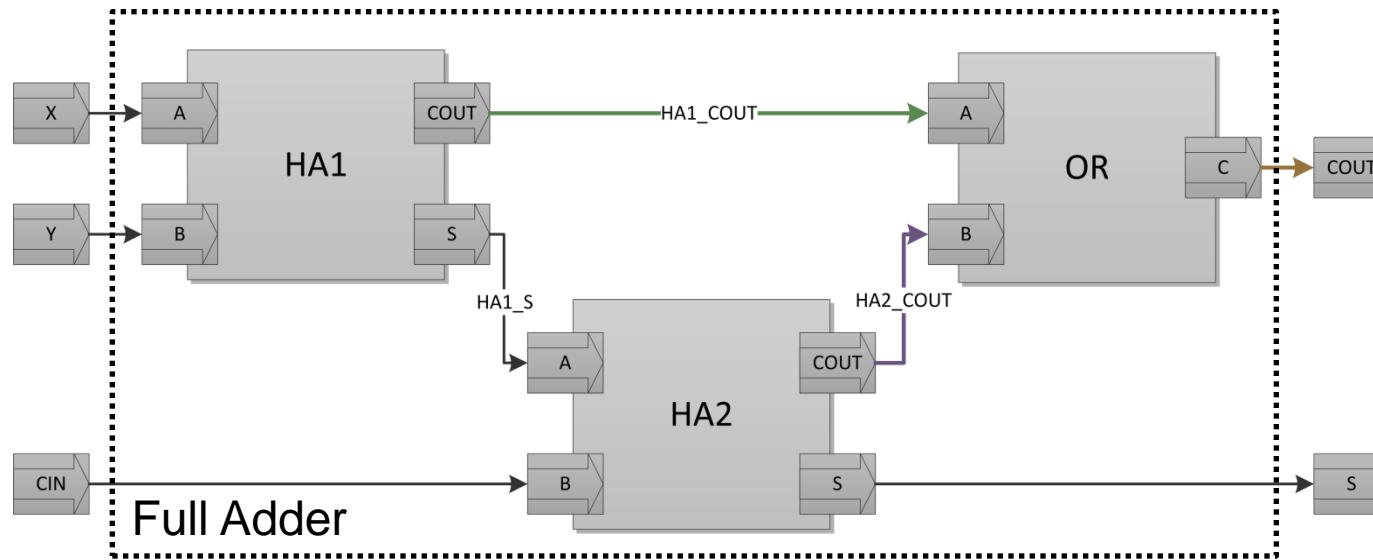


```

1 ha2 : half_adder
2     Port Map(
3         a          => ha1_s ,
4         b          => cin ,
5         s          => s ,
6         cout       => ha2_cout
7     );
  
```

Component instantiation of half adder in VHDL

# VHDL-Structural Description(3)



```
1  cout <= ha1_cout or ha2_cout;
```

Connection of OR-Gate in VHDL

# VHDL-Behavioural Description

## ■ VHDL Process

- Describes the behaviour of modules
- Executed in parallel

```
1  s <= a or b; --implicit process syntax
2
3  process( a, b ) --explicit process syntax
4  begin
5
6      if( a = '0' and b = '0' ) then
7          cout <= '0';
8      else
9          cout <= '1';
10     end if;
11
12 end process;
```

Behavioural description „or“ in VHDL

# Half Adder Code Example

```
1 library IEEE;
2 use IEEE.STD_LOGIC_1164.ALL;
3
4
5 entity half_adder is
6 PORT (
7         a          : in  std_logic;
8         b          : in  std_logic;
9         s          : out std_logic;
10        cout      : out std_logic
11 );
12 end half_adder;
13
14 architecture Behavioral of half_adder is
15
16 begin
17
18     s      <= a and b; --implicit process syntax
19
20 process( a, b ) --explicit process syntax
21 begin
22
23     if( a = not b) then
24         cout <= '0';
25     else
26         cout <= '1';
27     end if;
28
29 end process;
30
31 end Behavioral;
```

# Full Adder Code Example

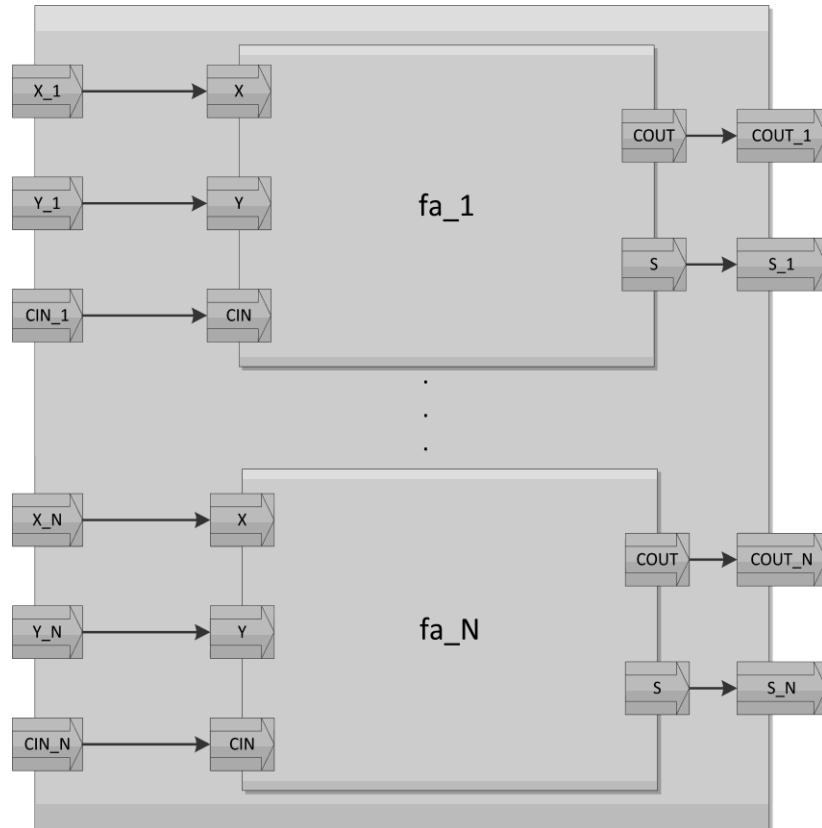
```

1
2 library IEEE;
3 use IEEE.STD_LOGIC_1164.ALL;
4
5
6 entity full_adder is
7     Port(
8         x          : in  std_logic;
9         y          : in  std_logic;
10        cin        : in  std_logic;
11        s          : out std_logic;
12        cout       : out std_logic
13    );
14 end full_adder;
15
16 architecture Behavioral of full_adder is
17
18 component half_adder
19     Port(
20         a          : in  std_logic;
21         b          : in  std_logic;
22         s          : out std_logic;
23         cout       : out std_logic
24    );
25 end component;
26
27 signal ha1_cout : std_logic;
28 signal ha1_s      : std_logic;
29
30
31 begin
32
33 ha1 : half_adder
34     Port Map(
35         a => x,
36         b => y,
37         s => ha1_s,
38         cout => ha1_cout
39     );
40
41 ha2 : half_adder
42     Port Map(
43         a => ha1_s,
44         b => cin,
45         s => s,
46         cout => ha2_cout
47     );
48
49 cout <= ha1_cout or ha2_cout;
50
51 end Behavioral;

```

# VHDL-Parallelism

- Modules can be instantiated multiple times and execute in parallel



Multiple Full Adders executing in parallel

```

1  fa_1 : full_adder
2      Port Map(
3          x => x_1,
4          y => y_1,
5          cin => cin_1,
6          cout => cout_1,
7          s => s_1
8      );
9
10 ..
11
12 fa_n : full_adder
13     Port Map(
14         x => x_n,
15         y => y_n,
16         cin => cin_n,
17         cout => cout_n,
18         s => s_n
19     );

```

Multiples instantiations of a Full Adder

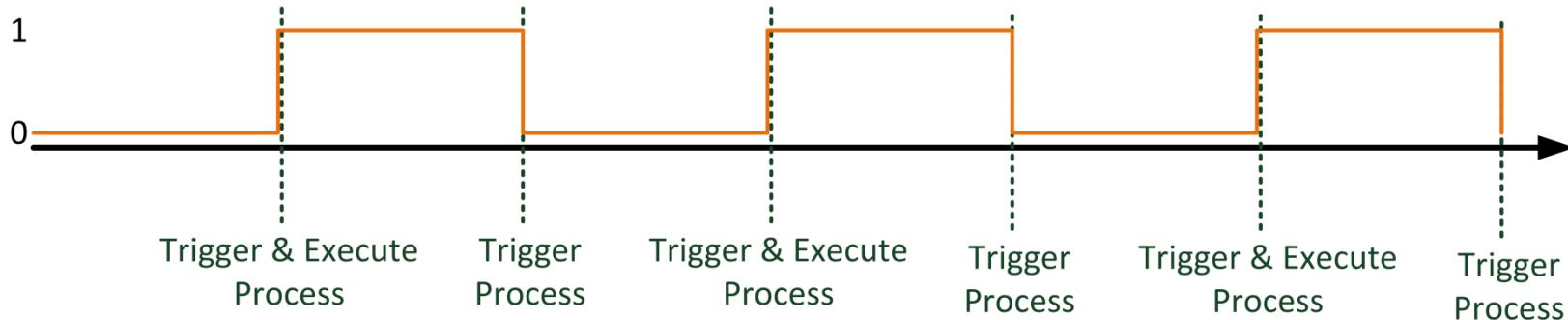
# VHDL-Clocking

- Using a clock for synchronisation in VHDL Modules
  - Clock signal included in **sensitivity list** of process
  - Rising or falling clock edge

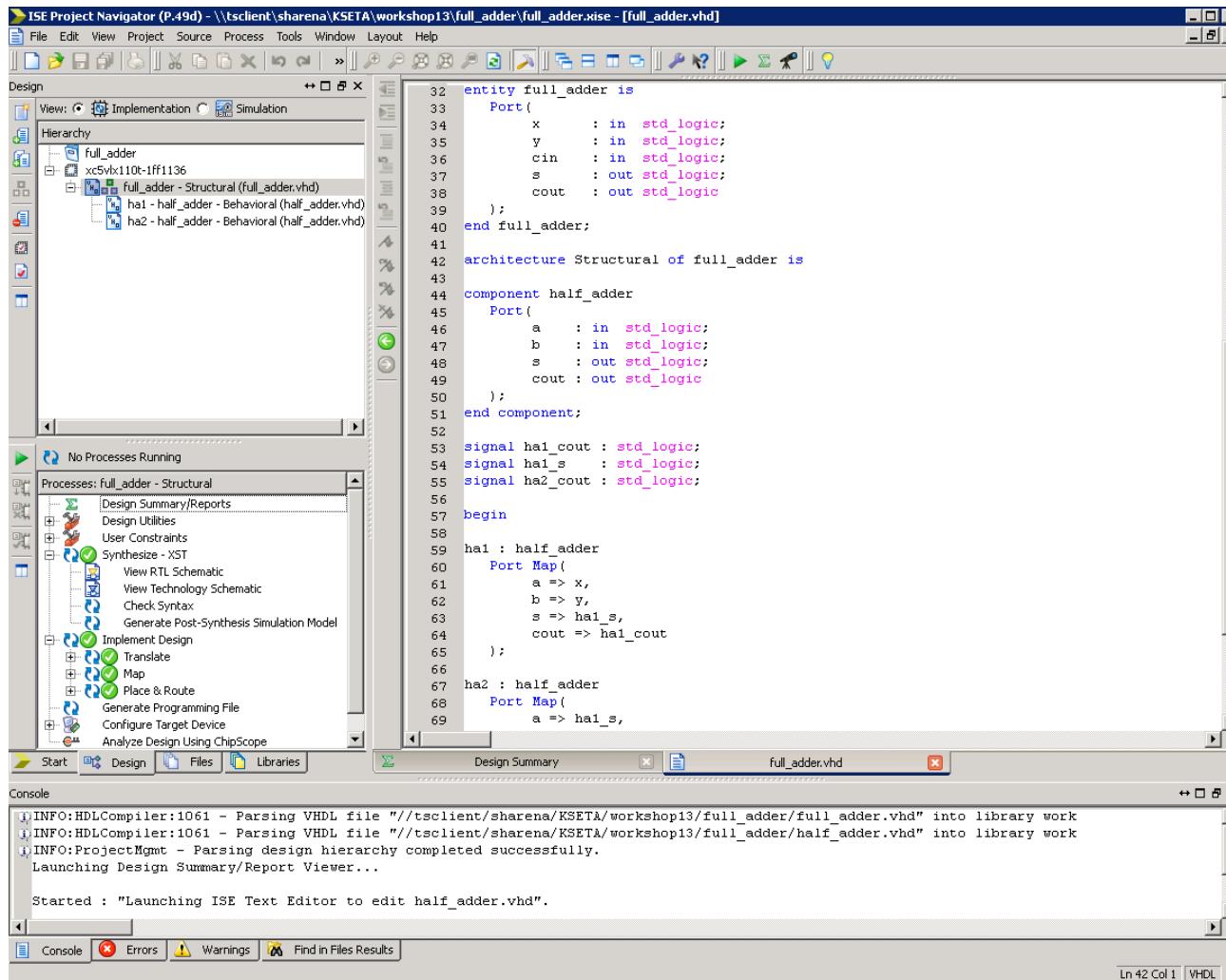
```

1 process(clk)
2 begin
3     if( clk = '1' and clk'event) then
4         result <= 1;
5     end if;
6 end process;

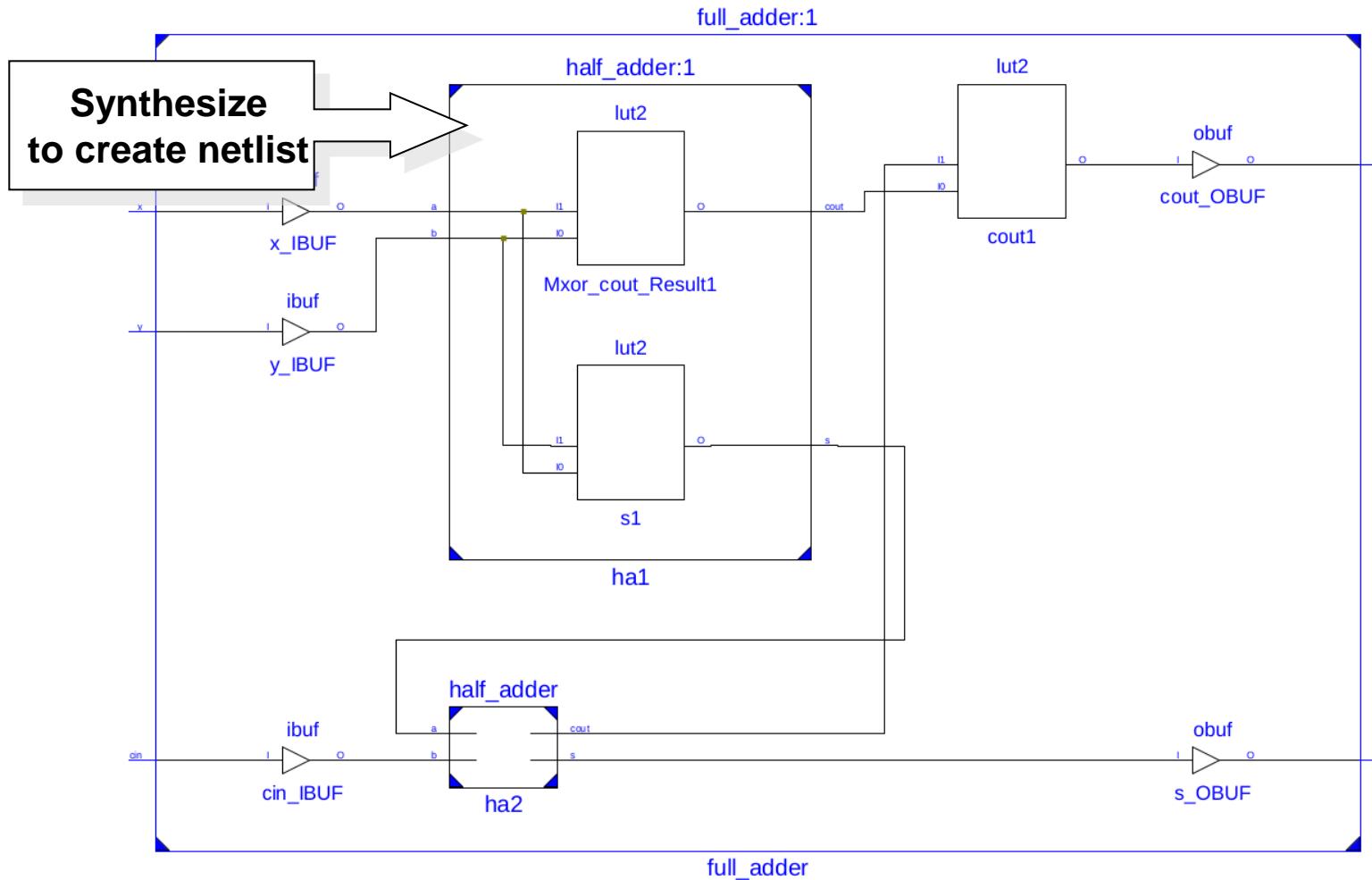
```



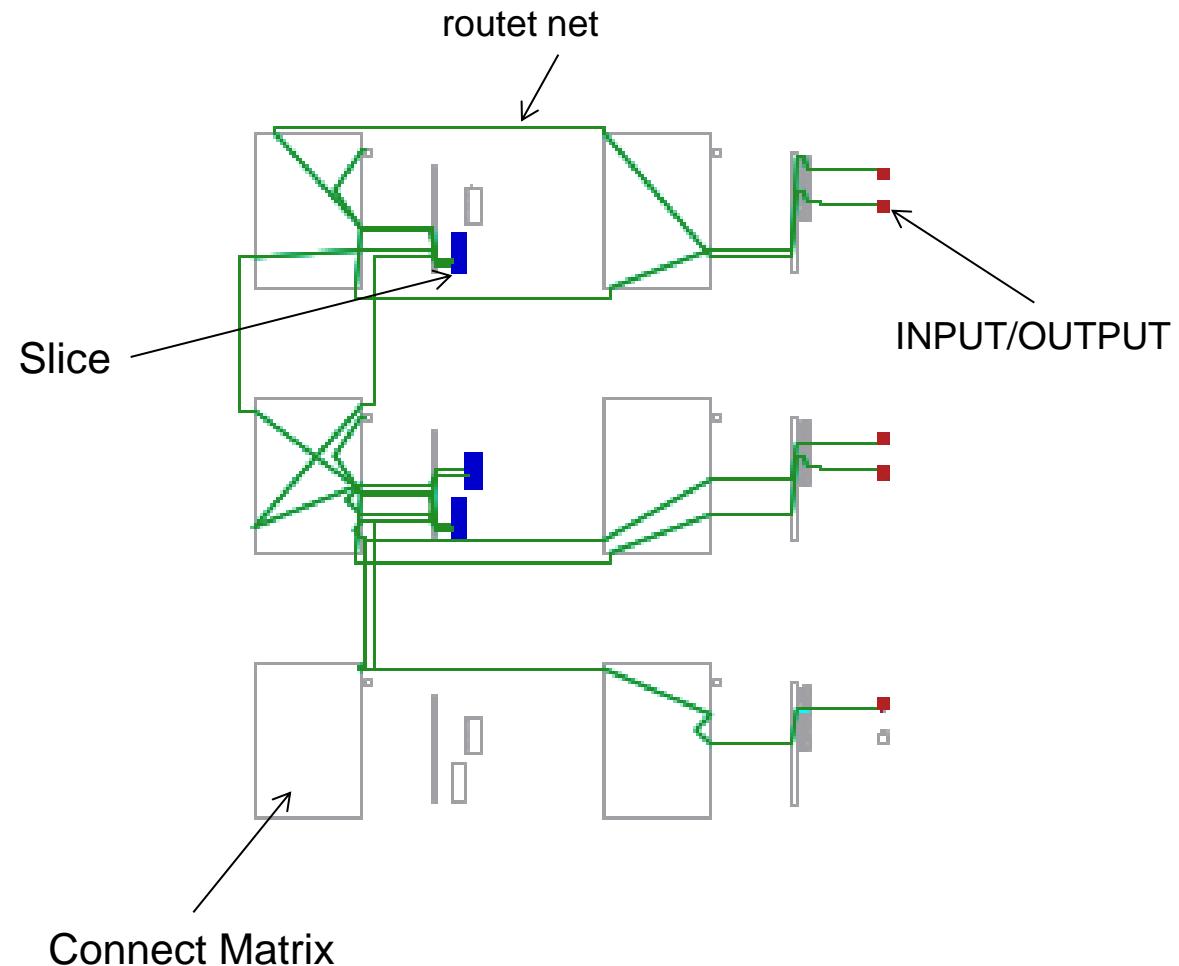
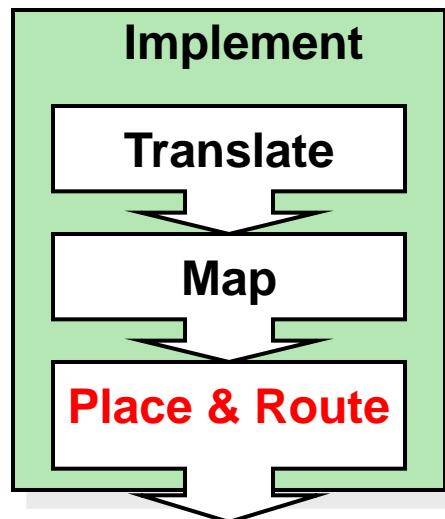
# XILINX Design Tool ISE



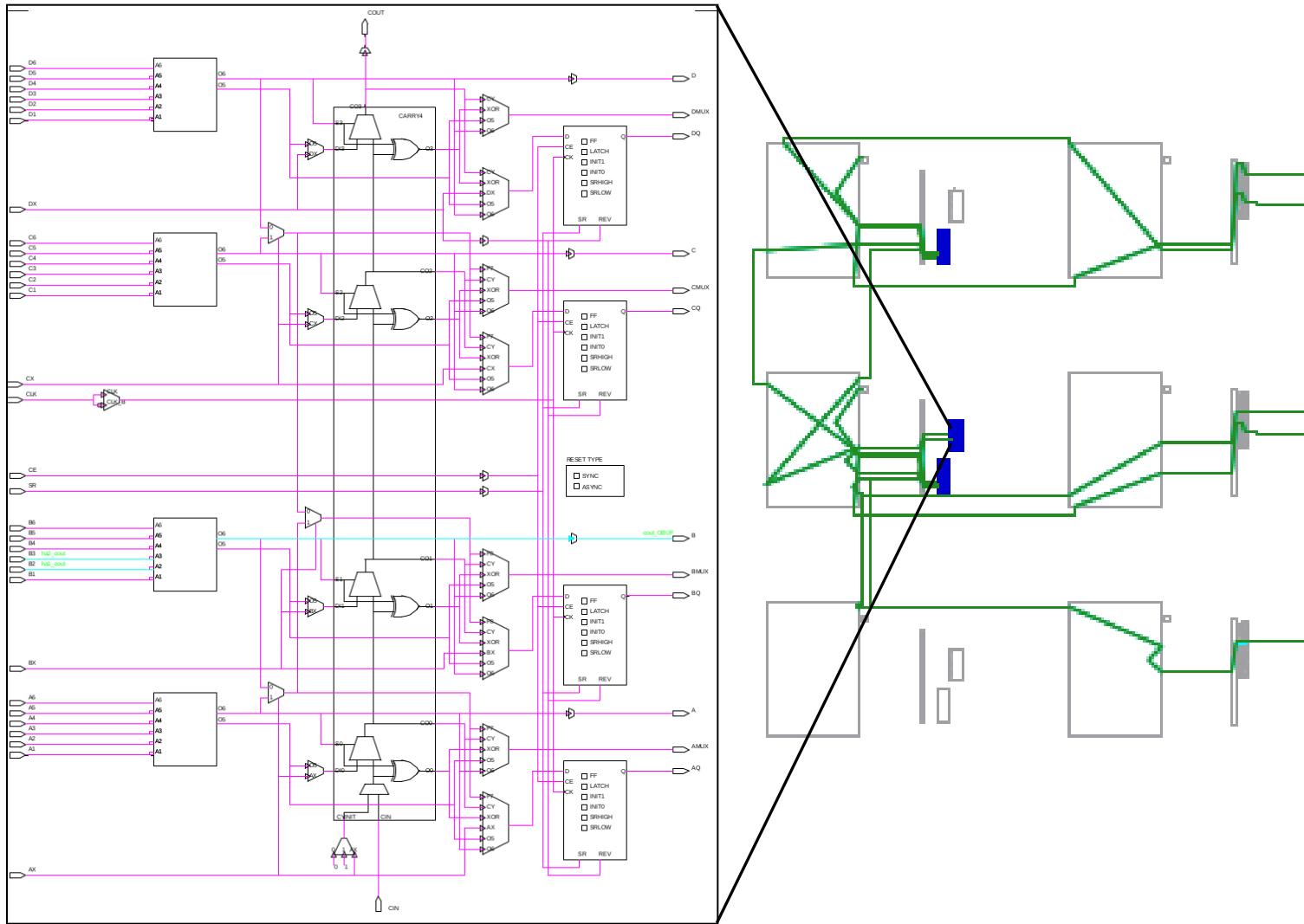
# Demo Synthesize



# Demo P&R



# Demo P&R

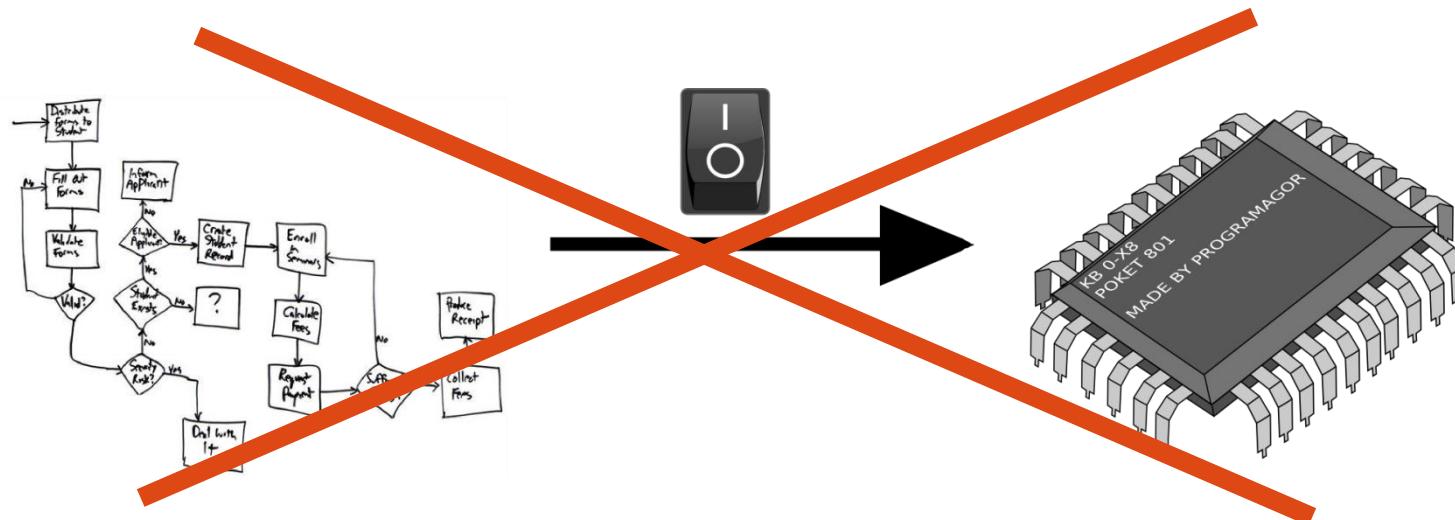


# High-Level-Design Approaches

- FPGA design by HDLs:
  - Time consuming
  - Error-prone
  - Difficult verification
  - Large teams
- Algorithms are not designed in HDL
- **Is there a faster/simpler way to design FPGAs?**

Yes! But ...

# Considerations for High-Level Approaches

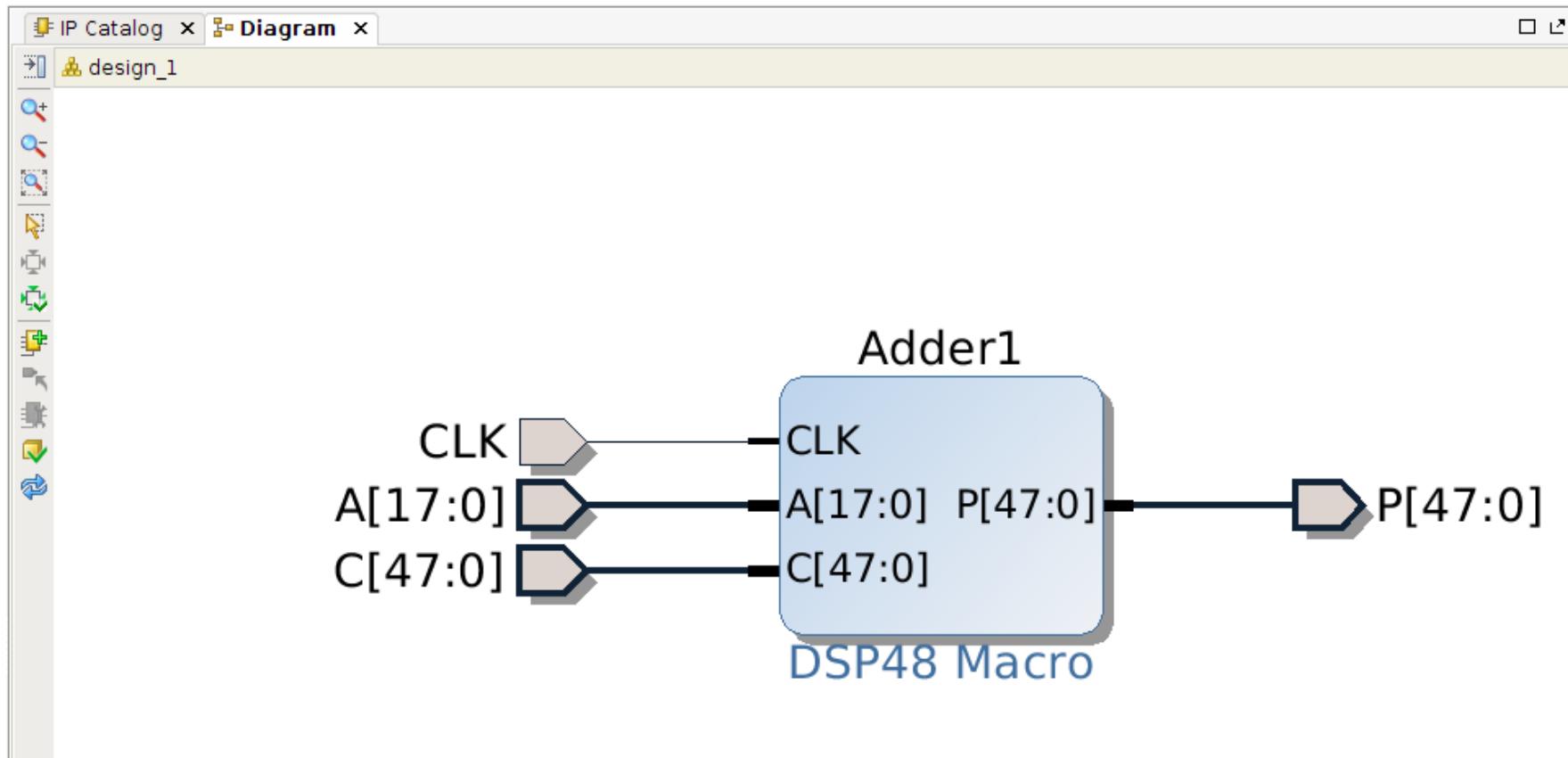


- There is no “Push-Button” approach
- Unlike for software compilation
- Designer must keep hardware in mind

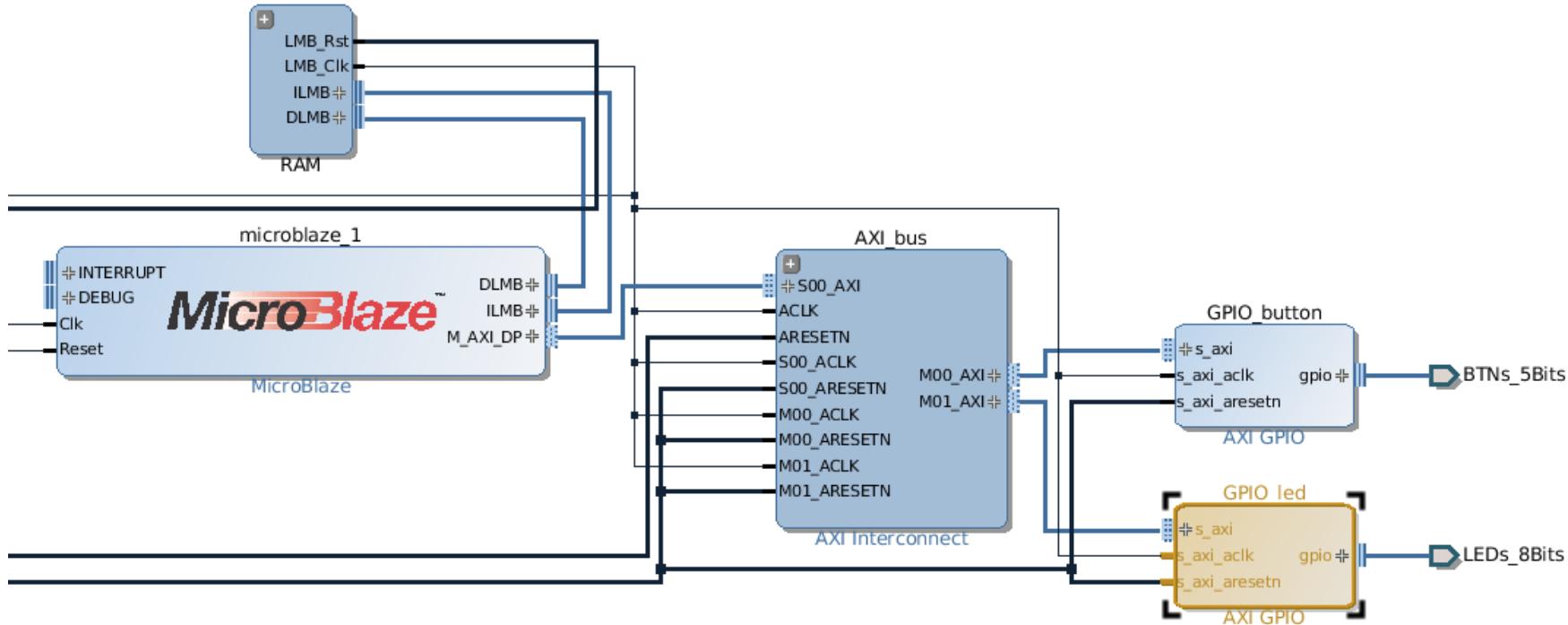
# System Designer

- Design of (Embedded) Systems based on building blocks
- IP-blocks connected by a standard bus
- Available blocks:
  - Arithmetics: Adder, Multiplier, sqrt, sin/cos, ...
  - Digital Signal Processing: FIR filters, FFT, ...
  - Processors, RAMs, ROMs, Peripheral controller, ...
- Limitations
  - Limited to the available blocks (included, purchased)
  - Describing a complex algorithm solely by basic blocks is cumbersome
- Applications: Altera Qsys / Xilinx EDK

# Xilinx EDK: Simple Adder



# Xilinx EDK: Complete Processor System



# High-Level-Synthesis (HLS)

- Converts an algorithm written in C/C++/SystemC to HDL
- C is used as most of its constructs could be supported
- Everything great?
  - Algorithm must be parallelizable
  - Data types should fit hardware
    - Minimal bit width which ensures the accuracy of algorithm
    - Floating point is expensive in hardware
  - Different optimization goals → Design Space Exploration
    - Throughput
    - Latency
    - Chip area
    - Power
- Applications: Xilinx Vivado HLS, Calypto Catapult

# Design Space Exploration (Example)

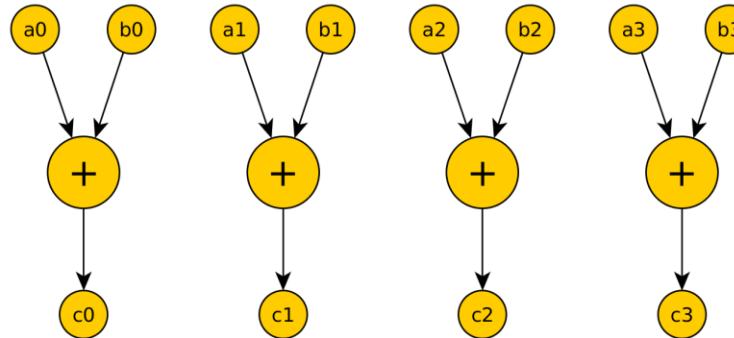
## ■ Vector Addition:

$$\begin{pmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} + \begin{pmatrix} b_0 \\ b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

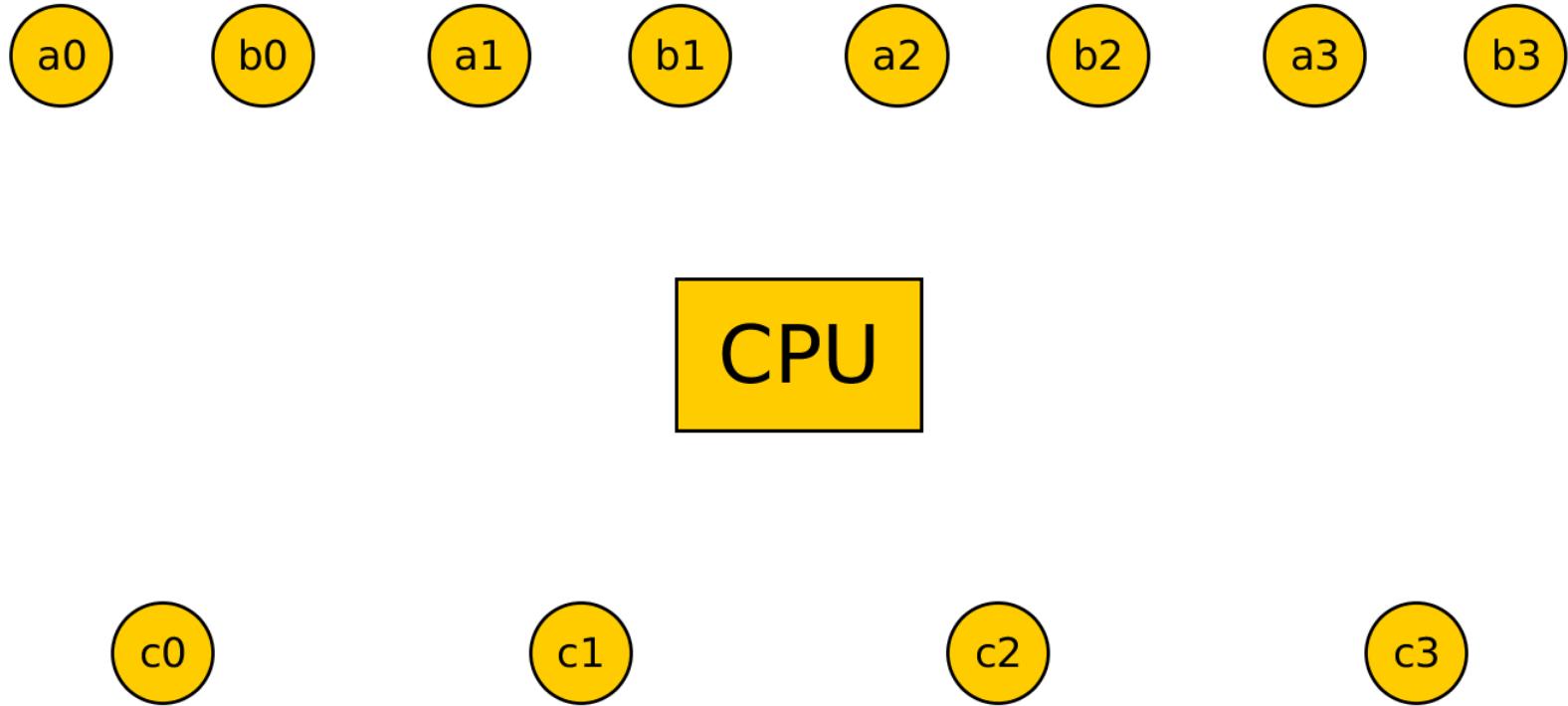
```

1 void addVectors( int a[], int b[], int c[], int n) {
2
3     for (int i=0; i<n; i++) {
4         c[ i ] = a[ i ] + b[ i ];
5     }
6
7 }
```

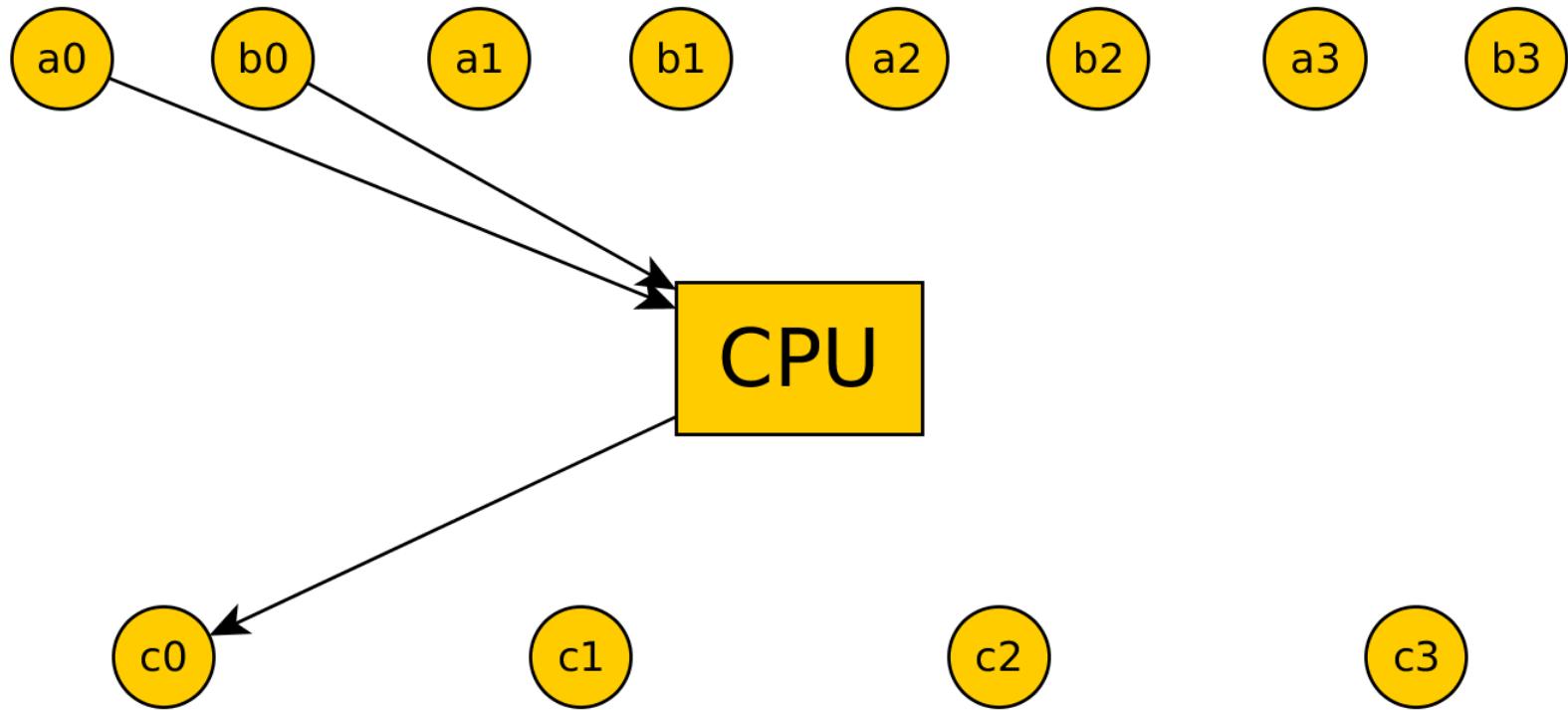
$n=4$ :



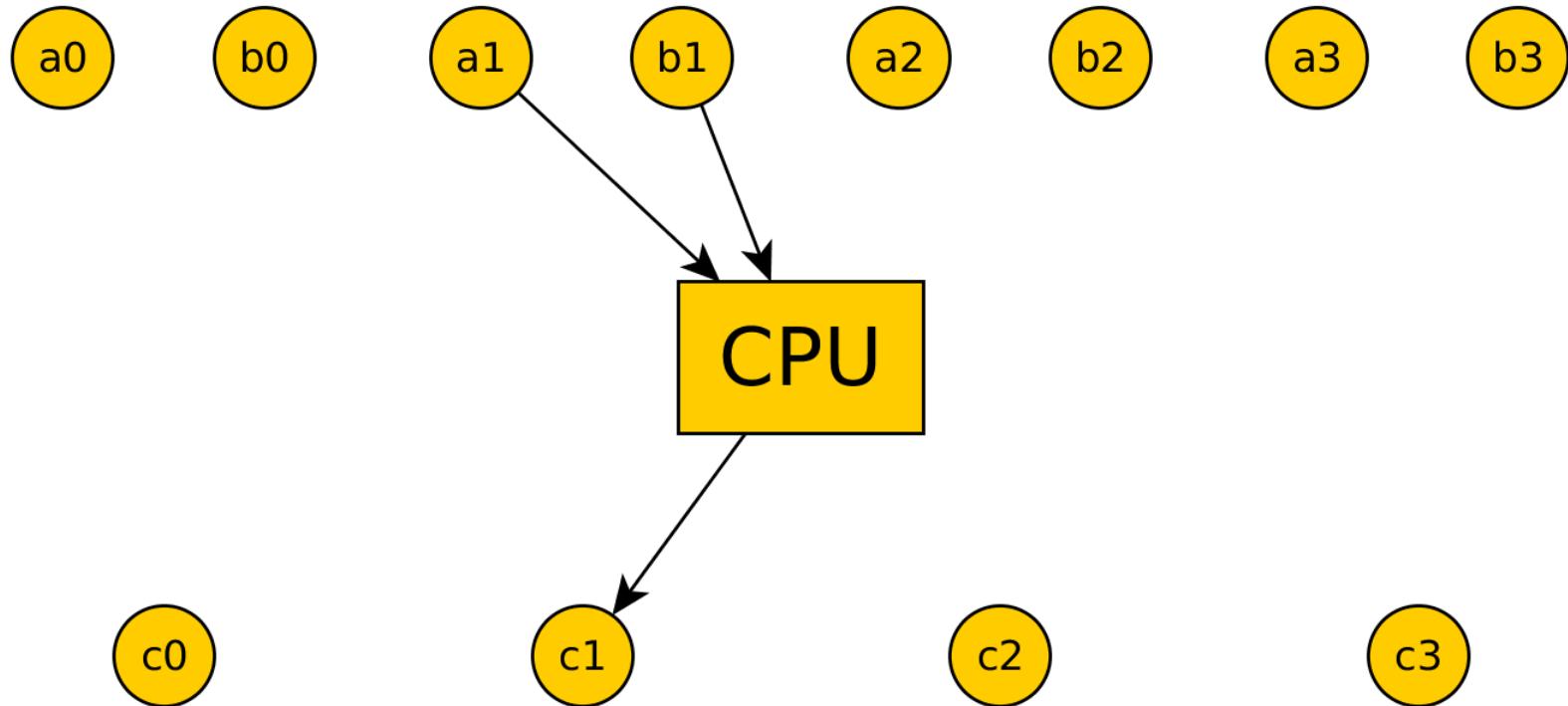
# Design Space Exploration – CPU / 1 Adder



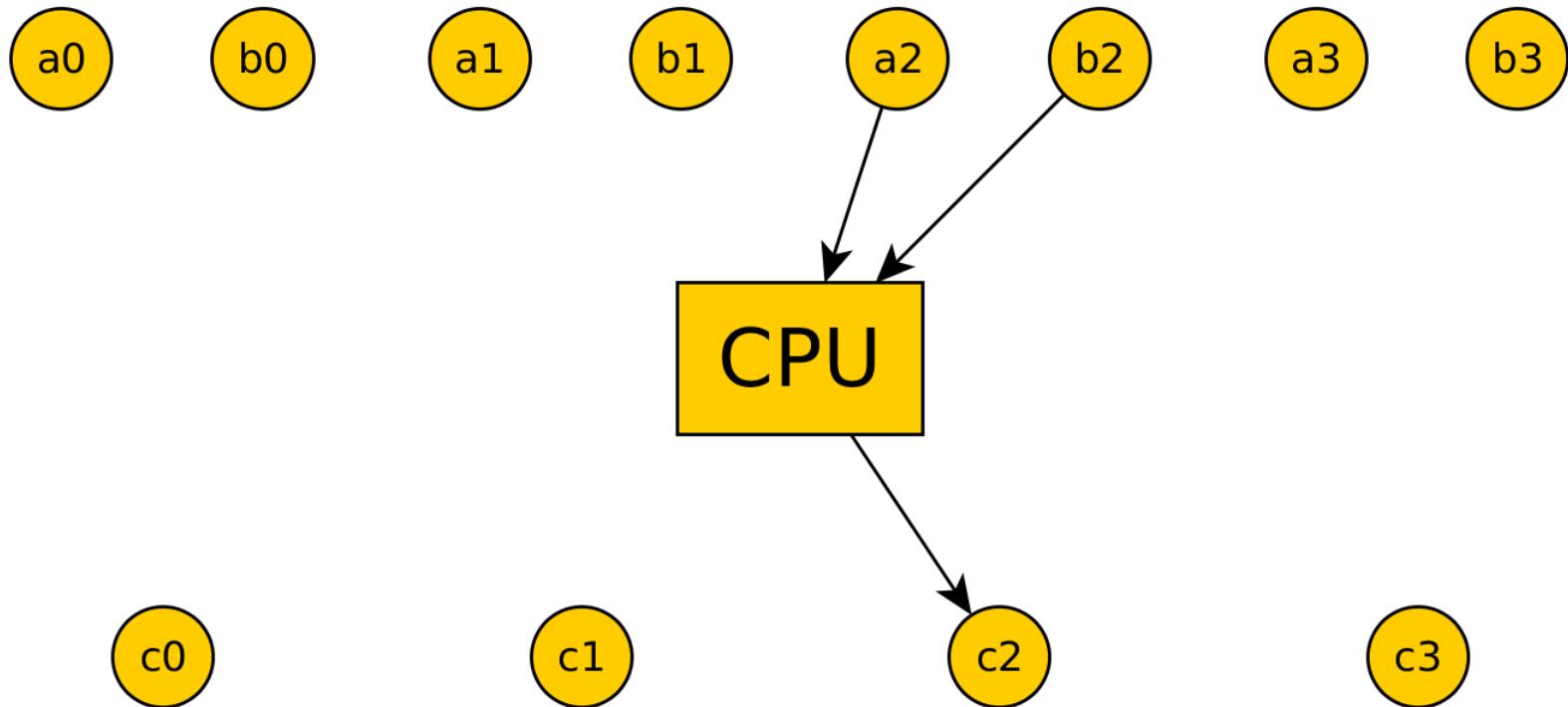
# Design Space Exploration – CPU / 1 Adder



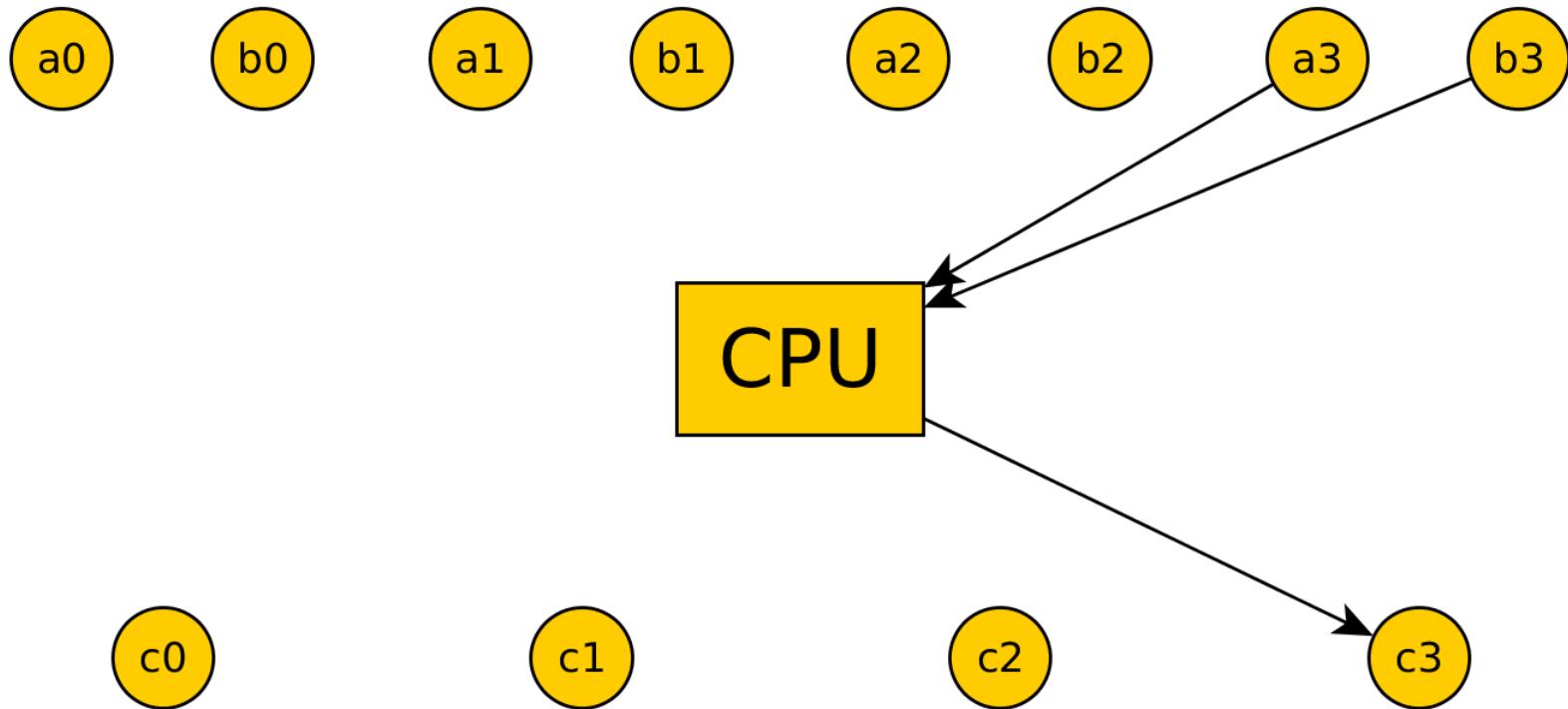
# Design Space Exploration – CPU / 1 Adder



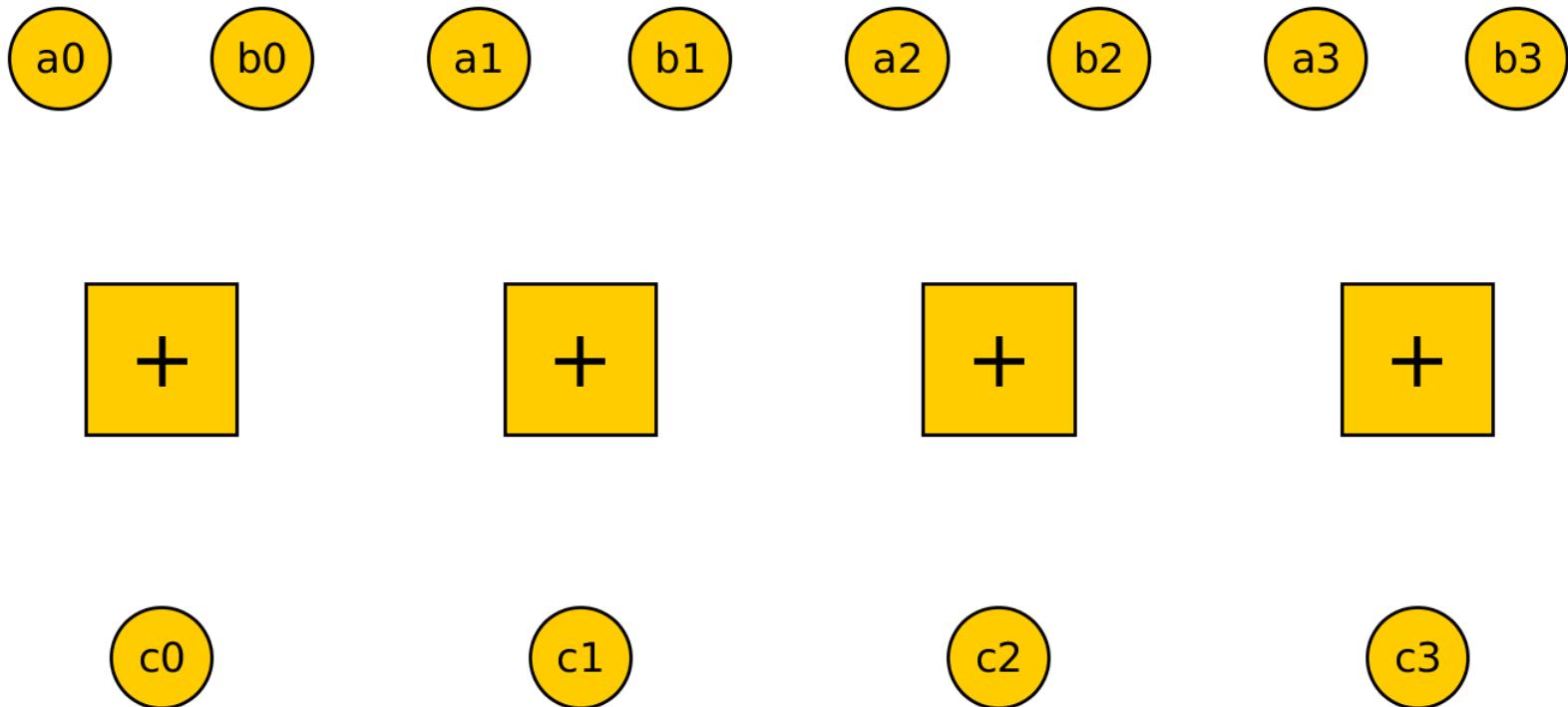
# Design Space Exploration – CPU / 1 Adder



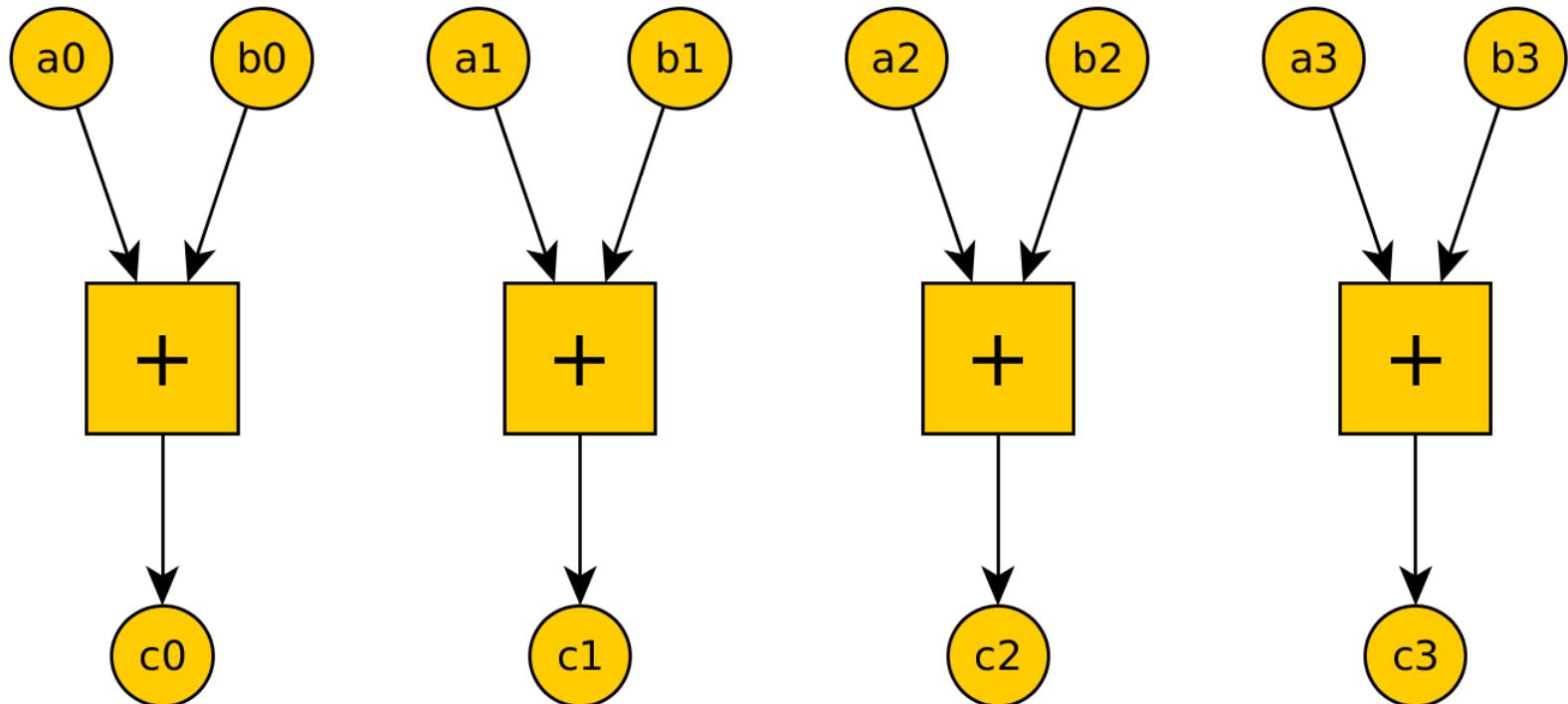
# Design Space Exploration – CPU / 1 Adder



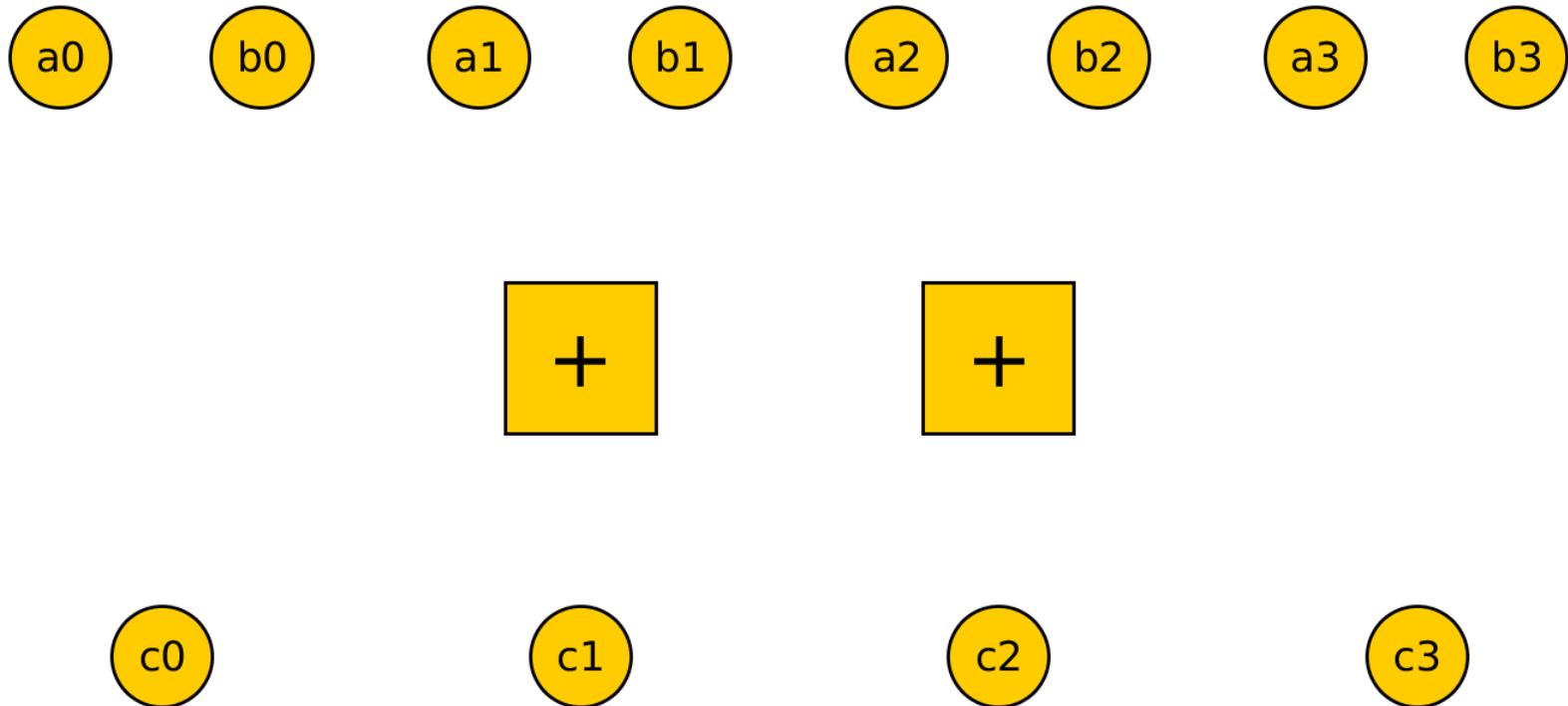
# Design Space Exploration – 4 Adder



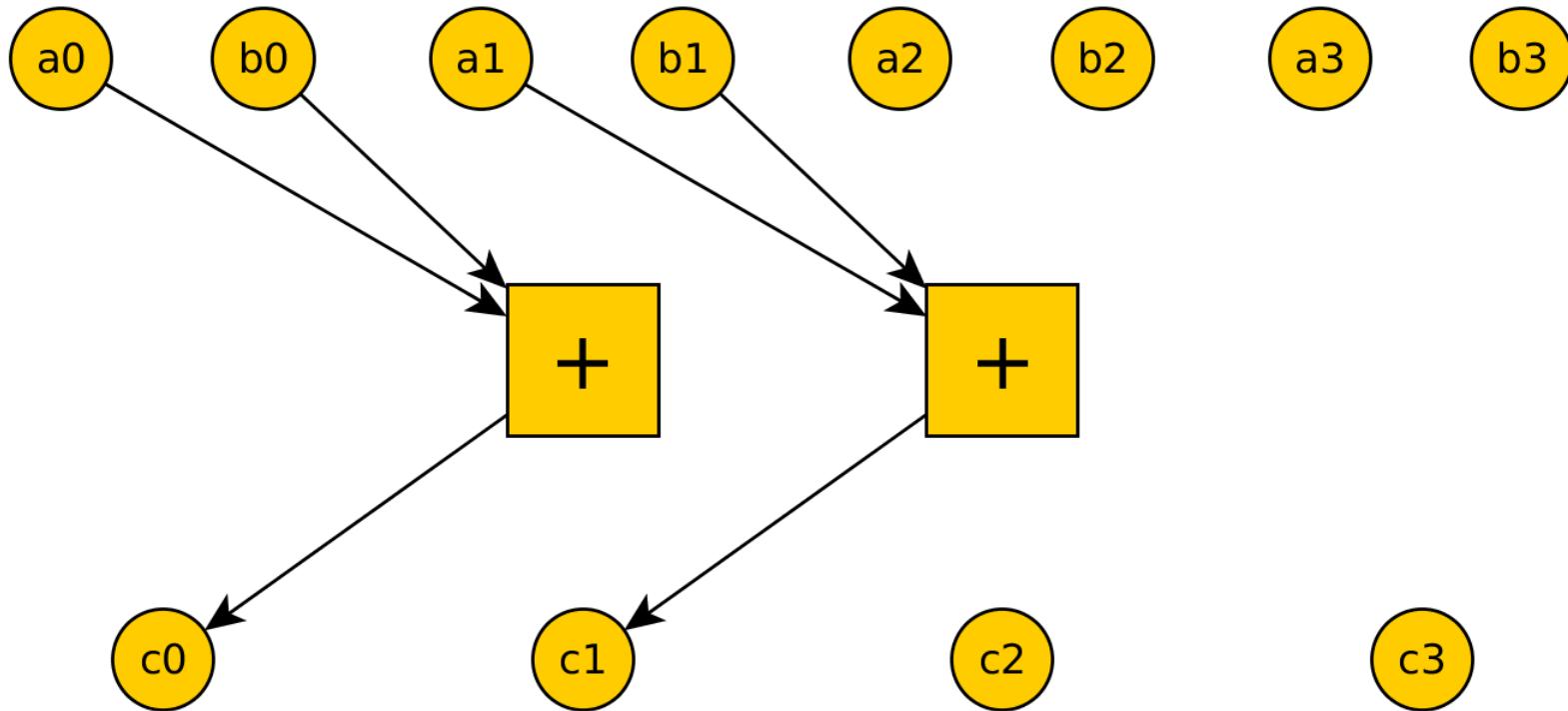
# Design Space Exploration – 4 Adder



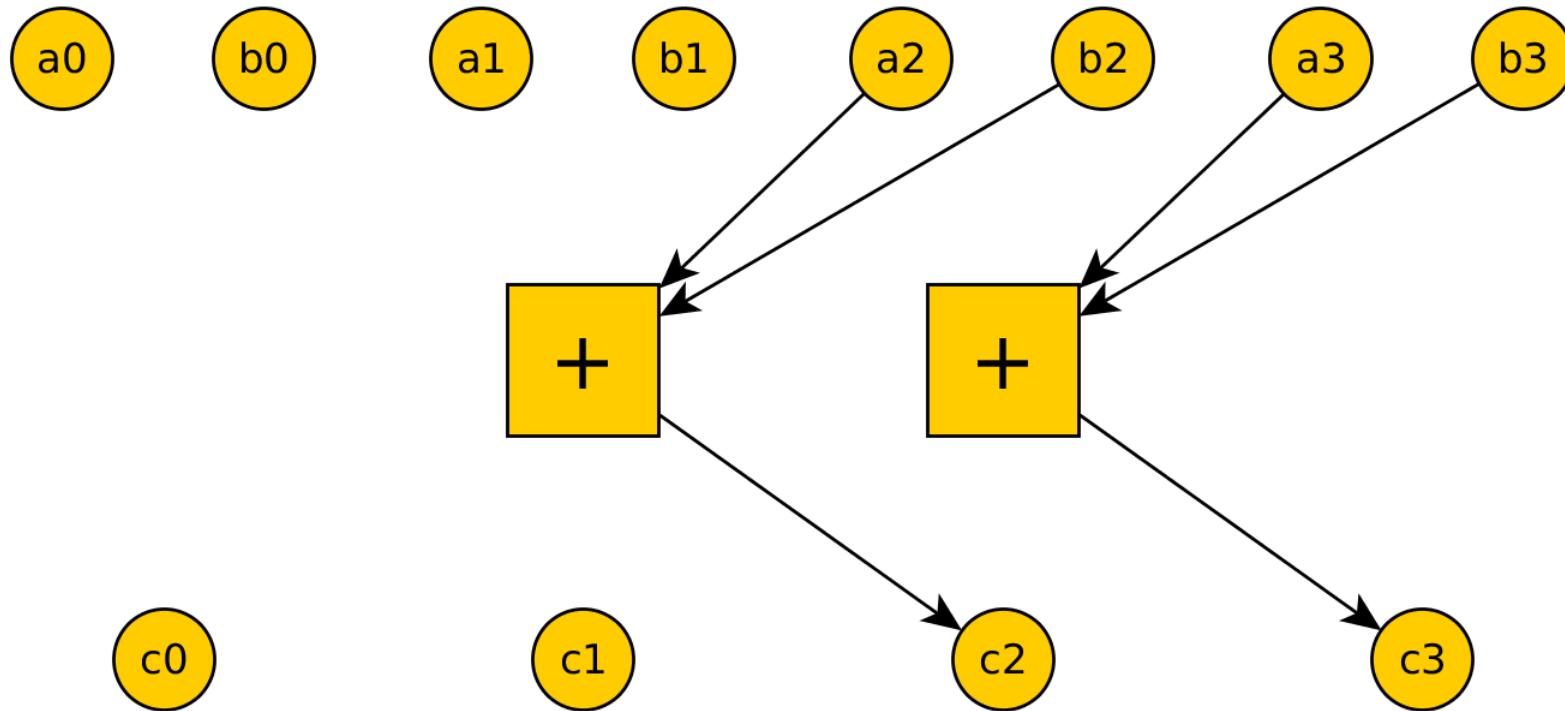
# Design Space Exploration – 2 Adder



# Design Space Exploration – 2 Adder



# Design Space Exploration – 2 Adder

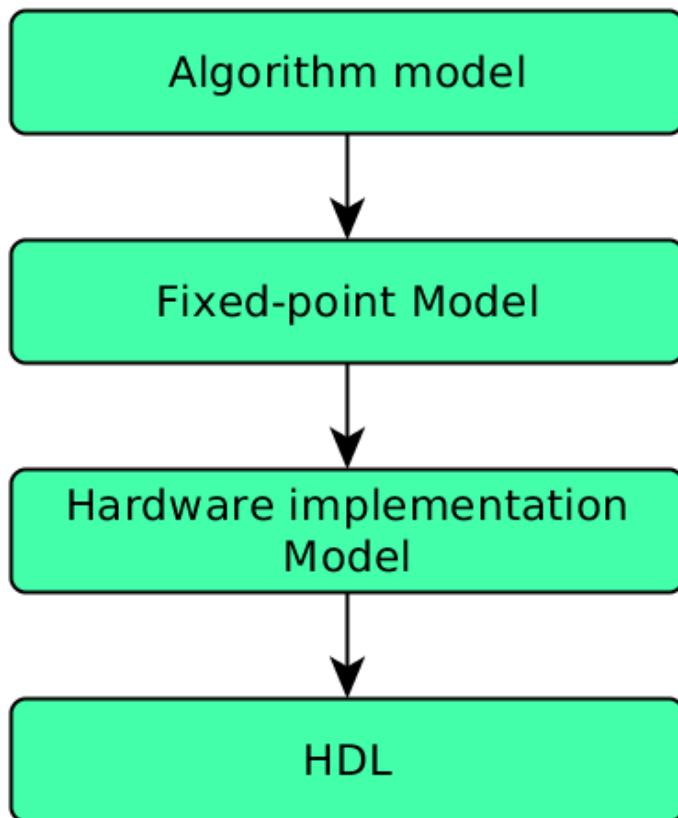


# Design Space Exploration – Comparison

	CPU	1 Adder	2 Adder	4 Adder
Area	1.2	1	2	4
Results/Cycle	0.25	0.25	0.5	1
Clock [MHz]	600	400	400	400
Throughput [MOPs]	150	100	200	400

- There is not a single optimal solution
- Many of these optimizations needs to be done manually

# Simulink / Matlab



- Graphical FPGA Design
- Many Simulink blocks supported
- Verification is integrated
  
- Examples:
  - Mathworks HDL Coder
  - Altera DSP Compiler
  - Xilinx System Generator

# Open Computing Language (OpenCL)

- Extension to standard C
- Description of massively parallel algorithms
- Kernels describe parallel parts of algorithms
- Kernel could execute on different computation units
  - CPU
  - GPGPU
  - FPGA
- Limitations:
  - No stand alone FPGAs – Kernels called by host program
  - (so far) only 1 FPGA board supported
- Application: Altera SDK for OpenCL

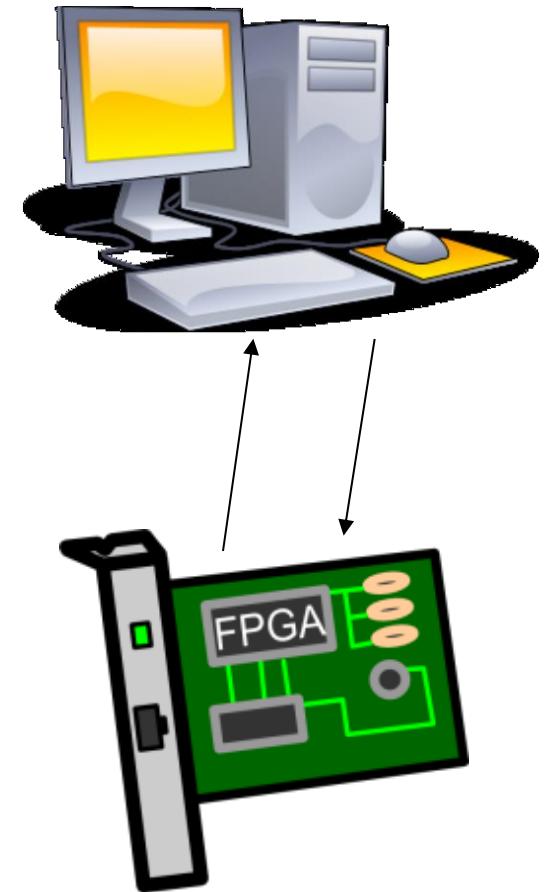
# OpenCL – (very simplified) Example

```

1 int main() {
2   a = readMatrixFromFile();
3   b = readMatrixFromFile();
4
5   ConfigureAndCompileKernel();
6   CopyDataToDevice();
7
8   RunKernel( addVectors ,a ,b ,c , vector_length )
9
10  CopyDataToHost();
11  PrintMatrix(c);
12 }
```

```

1 __kernel void addVectors(a, b, c, n) {
2
3   i = get_global_id(0);
4
5   c[ i ] = a[ i ] + b[ i ];
6 }
```

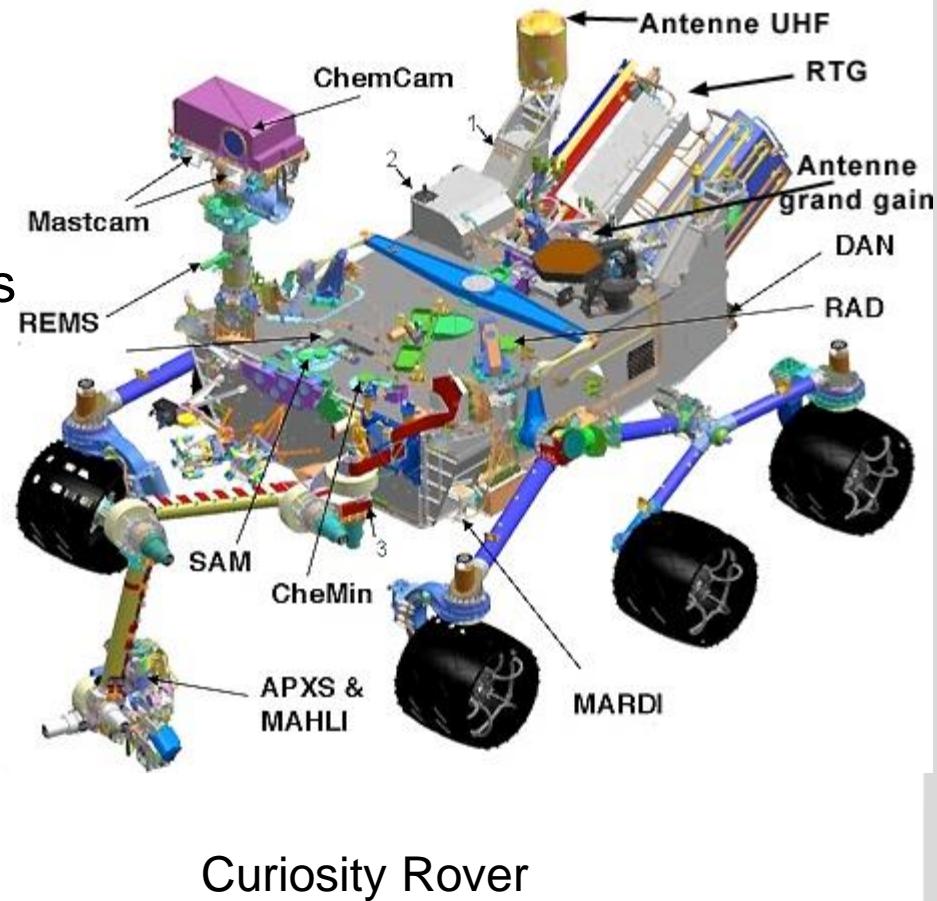


# FPGA - Applications

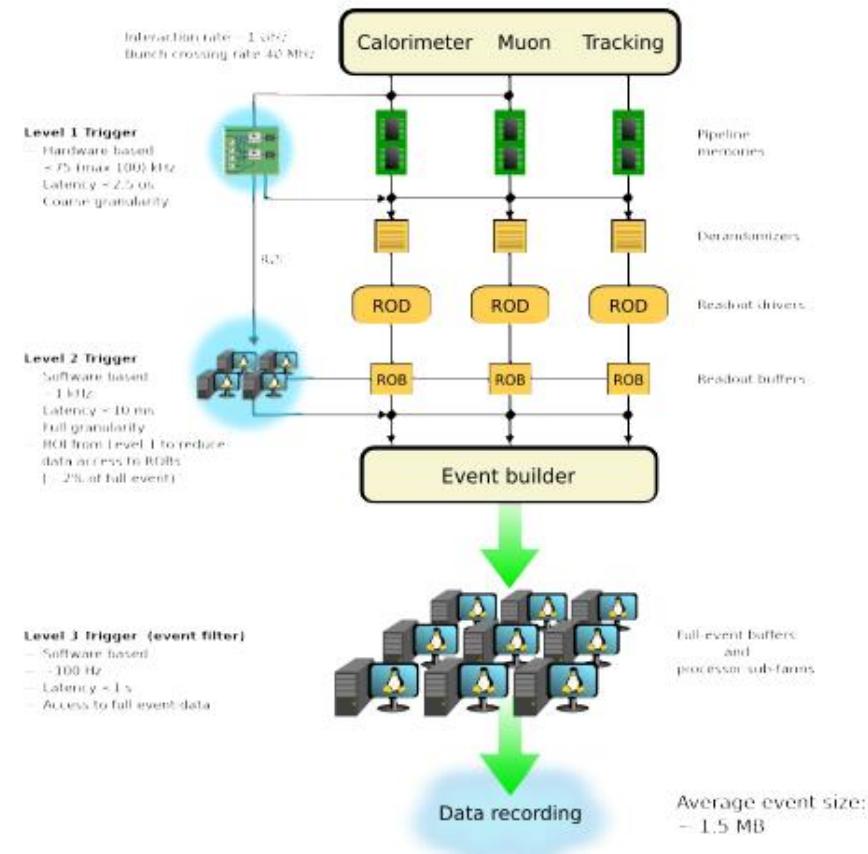
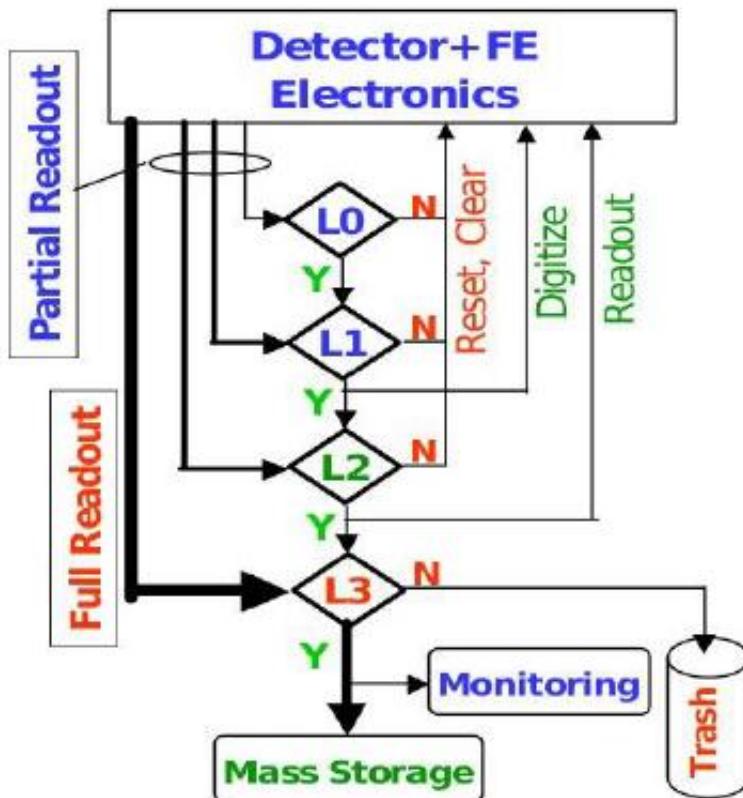
- Digital signal processing
- ASIC prototyping
- Computer vision
- Military applications
- Medical applications
- Automotive applications
- Consumer electronics
- Industrial applications
- High performance computing
- Space and aeronautics

# Mars exploration rovers (MER)

- Rad tolerant Xilinx XQVR FPGA
- Control of the pyrotechnic operations during descent and landing procedure
- Control of the motors for the wheels, steering, arms, cameras, instrumentation
- On-board re-programmability allowed design changes and updates even after the rover has landed



# Trigger and DAQ systems in particle physics



FPGA-based trigger for  
NA62 Experiment

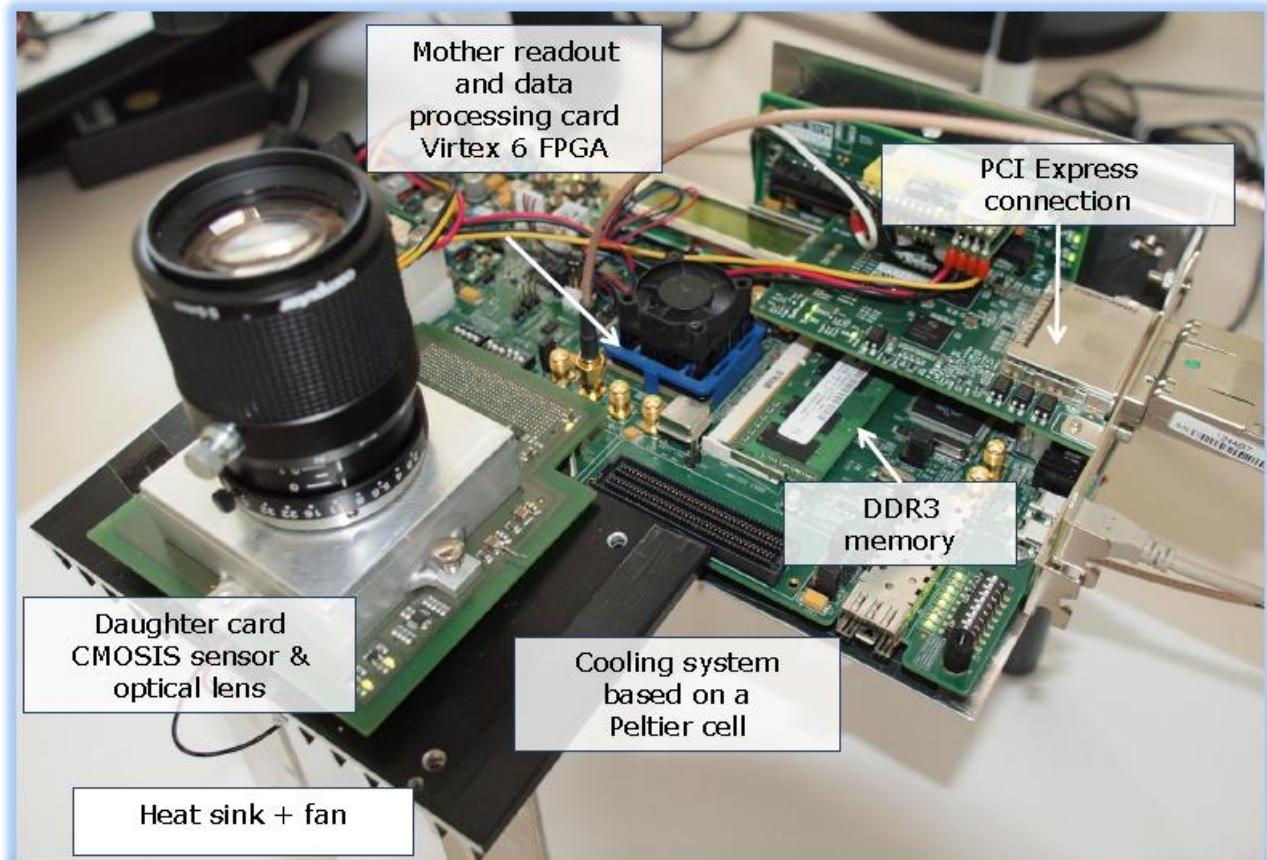
ATLAS Trigger system  
L1 is hardware based

# Banking applications

- Calculating company's collateral debt obligation (CDO) in near real-time
- Prior to the FPGA solution, main risk model for analyzing CDO portfolio took 8-12 hrs, based on x1000 x86 cores → in case of error, no time to resubmit for the day!
- With the speedup, same risk model took 4 minutes → multiple scenarios throughout the day
- Final hardware system is 40-node hybrid cluster
- Each cluster contains 8 Xeon (24GB) cores with 2 FPGA (Xilinx Virtex 5) (12GB)
- Time-critical, compute-intensive pieces of C++ risk model was ported to FPGA
- Advantage of the FPGA → exploit of the fine-grained parallelism and pipelines → many more calculations per watt vs. the CPU

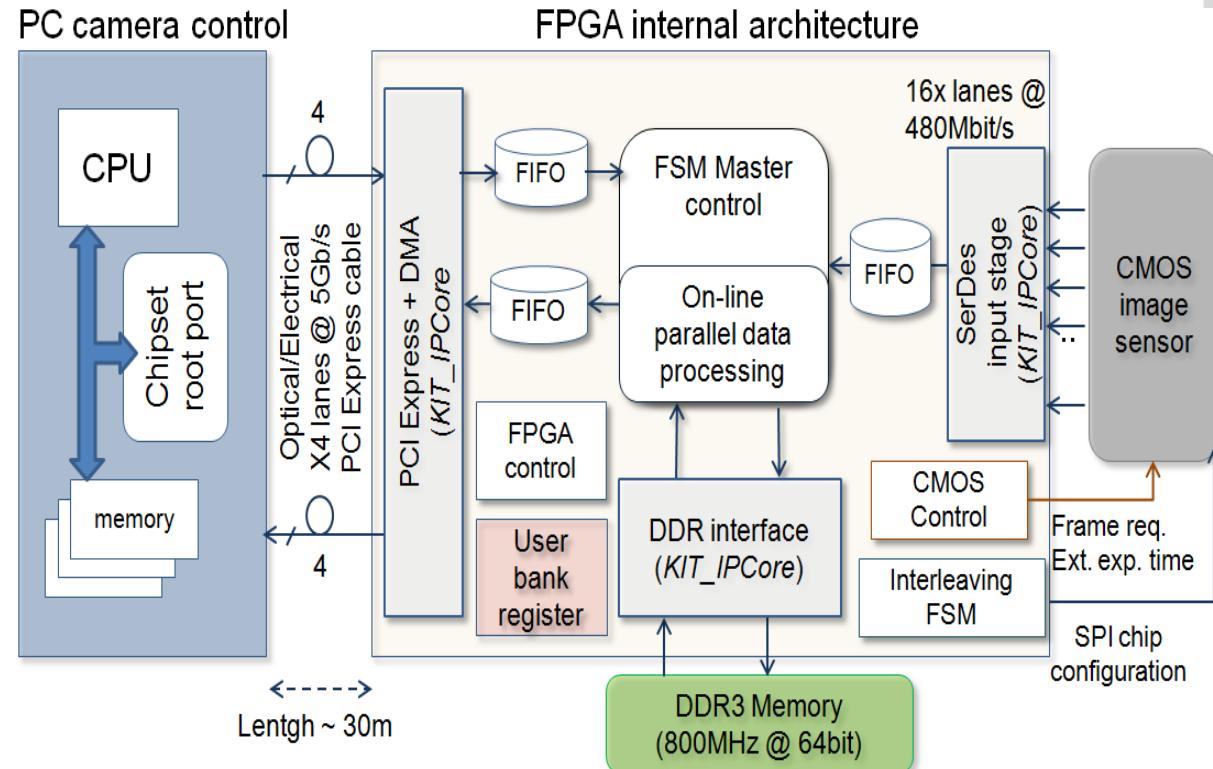
# KIT UFO camera

- Ultra Fast X-ray imaging of scientific processes with On-line assessment and data-driven process control
- High-speed data transfer
- Image-based process control
- Programmable camera
- On-camera image processing



# Readout chain and FPGA architecture

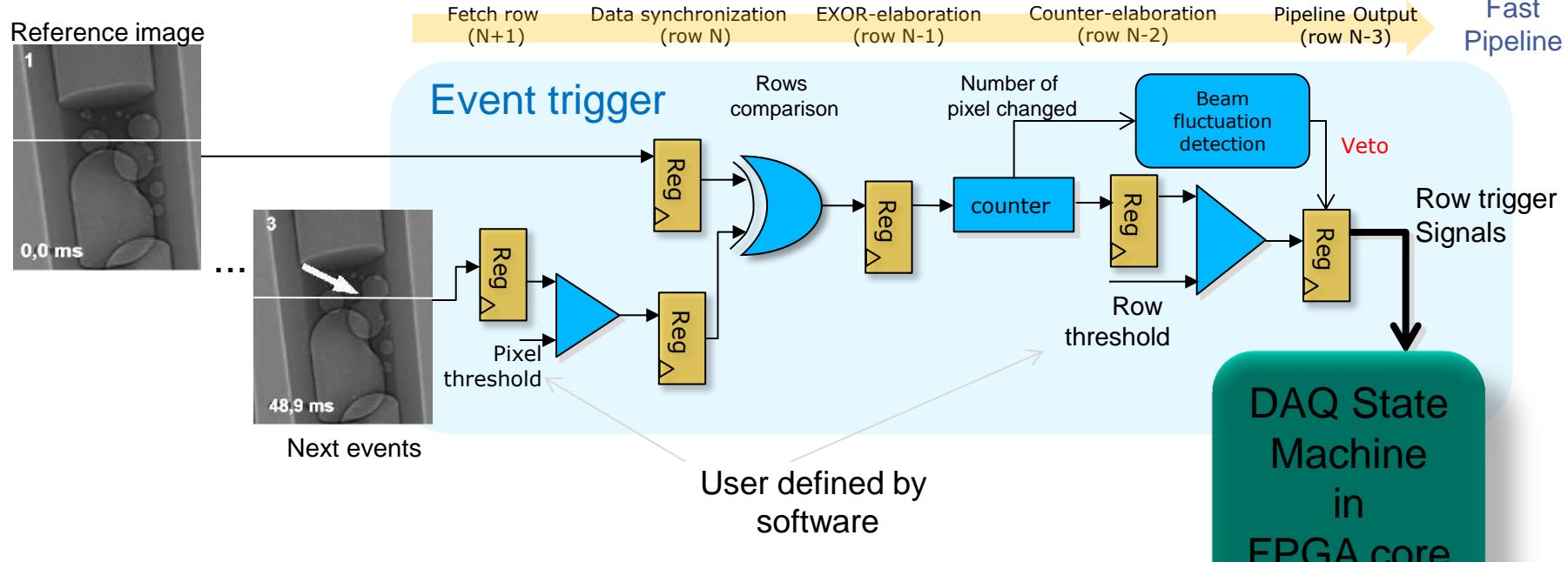
- 2.2 MP CMOS sensor
- 340 fps @ full view
- 14 Gb/s streaming with Bus Master DMA
- Virtex-6 Xilinx FPGA



# Sub-sampling strategy for rows 'fast reject'

Generating fast reject signals (triggers) @ rows level → starting from a reference image

Subsampling strategy is used to allow a fast readout frame @ kHz range

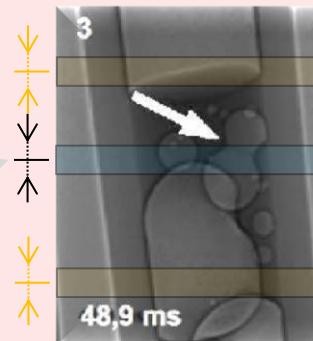


## Event Readout

To limit the amount of data and increase the frame rate from sensor, **windowing** in Y direction is possible. The number of lines and start address can be set by SPI

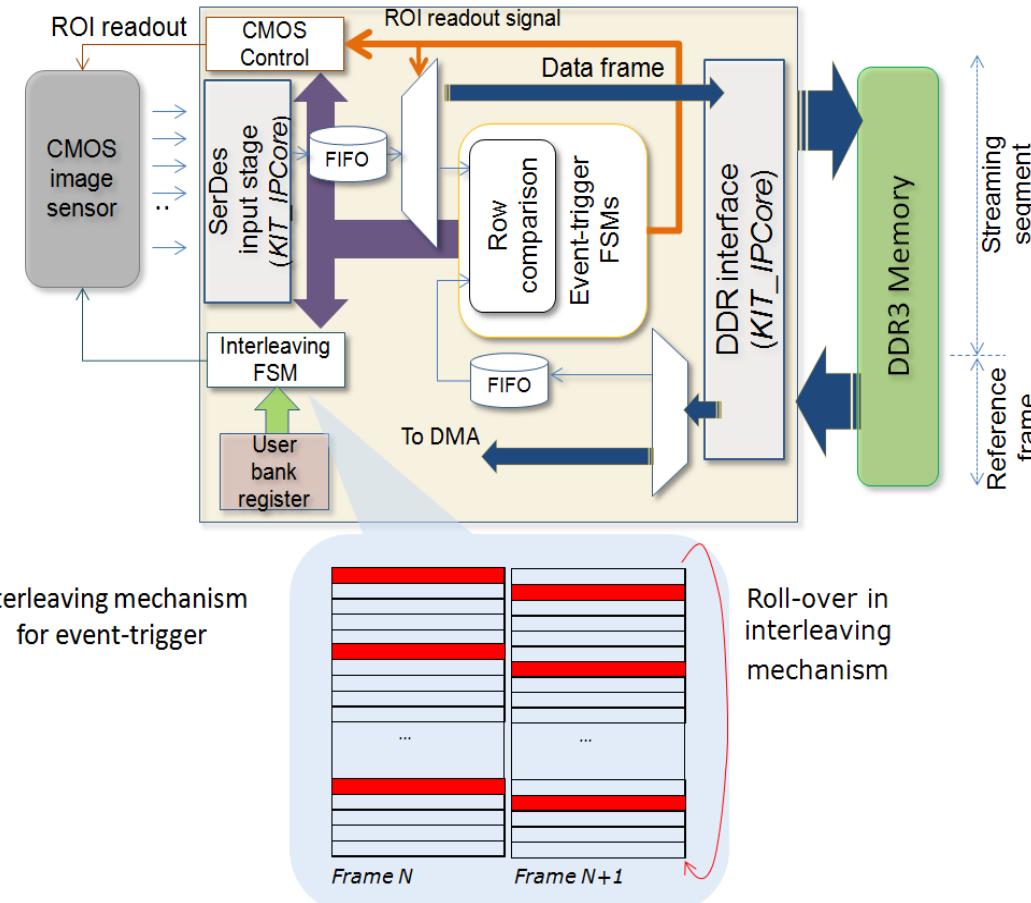
Readout of a window around the row trigger signal or full frame can be requested

Optionally the multiple windows can be defined when a multiple rows trigger are presents

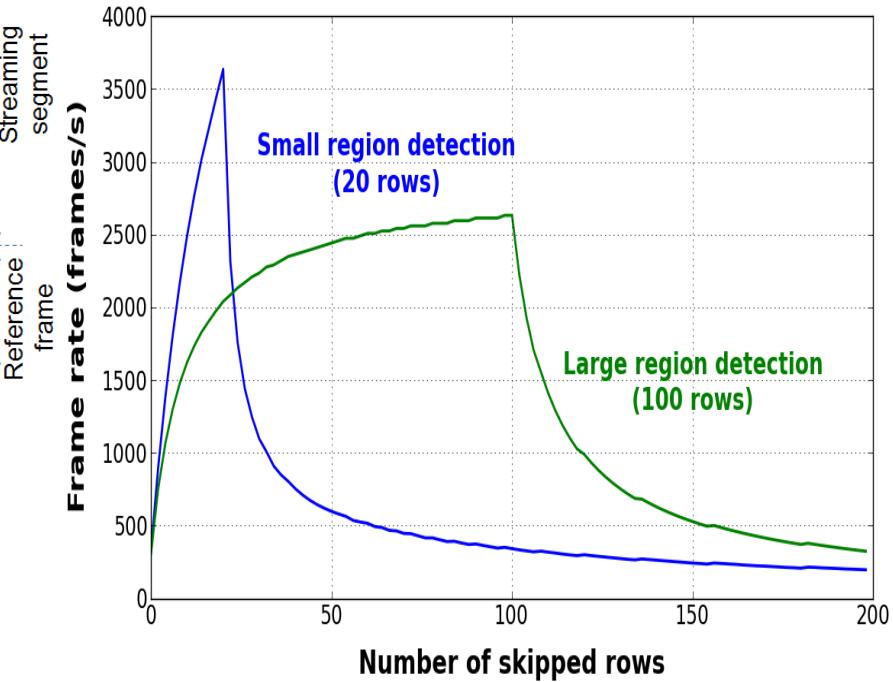


SPI chip configuration signals

# Image based trigger – architecture and performance



## FPGA architecture



## Performance

# CPU, GPU vs. FPGA

Often FPGAs and CPU/GPU are complementary: they co-exist in the same system and perform different tasks.

FPGA Advantages	CPU/GPU Advantages
<ul style="list-style-type: none"><li>• more flexible processing</li><li>• more flexible input/output</li><li>• parallel processing</li><li>• multi-clock</li><li>• timing operations</li><li>• highly customizable</li><li>• “real-time” applications</li></ul>	<ul style="list-style-type: none"><li>• programming a CPU is normally easier than programming an FPGA (no understanding of the digital electronics)</li><li>• faster compilation</li><li>• easier code portability</li><li>• lower unit costs - for any volume</li><li>• GPU offers massive parallel execution resources and high memory bandwidth</li><li>• “fast” applications</li></ul>

# Applications suitability for GPU and FPGA

	FPGAs	GPUs	
Good fit	Computations involves lots of detailed low-level hardware control operations, with no efficient implementation in high level language	No independence in the data flow and computation can be done in parallel	Good fit
	A certain degree of complexity is required and the implementation take advantage of data streaming and pipelining	Applications contain a lot of parallelism but involve computations which cannot be efficiently implemented on GPUs	
Poor fit	Applications that require a lot of complexity in the logic and data flow design	Applications have a lot of memory accesses and have limited parallelism	Poor fit

# Q & A